
Nonparametric Inference with Gaussian Process Priors

Aad van der Vaart Harry van Zanten
Vrije Universiteit Amsterdam

May 2007



Motivation

The Bayesian Choice
Outline

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

Motivation



The Bayesian Choice

Motivation

The Bayesian Choice

Outline

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

The Bayesian paradigm is an elegant and unified approach.



The Bayesian Choice

Motivation

The Bayesian Choice

Outline

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

The Bayesian paradigm is an elegant and unified approach.

According to the complete class theorem (e.g. Le Cam, 1964) the set of Bayes procedures is sufficiently rich to dominate every statistical procedure.



The Bayesian Choice

Motivation

The Bayesian Choice

Outline

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

The Bayesian paradigm is an elegant and unified approach.

According to the complete class theorem (e.g. Le Cam, 1964) the set of all **limits of** Bayes procedures is sufficiently rich to dominate every statistical procedure.



The Bayesian Choice

Motivation

The Bayesian Choice

Outline

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

The Bayesian paradigm is an elegant and unified approach.

According to the complete class theorem (e.g. Le Cam, 1964) the set of all **limits of** Bayes procedures is sufficiently rich to dominate every statistical procedure.

Does it work in nonparametrics?



The Bayesian Choice

Motivation

The Bayesian Choice

Outline

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

The Bayesian paradigm is an elegant and unified approach.

According to the complete class theorem (e.g. Le Cam, 1964) the set of all **limits of** Bayes procedures is sufficiently rich to dominate every statistical procedure.

Does it work in nonparametrics?

Frequentist study:

We use the Bayesian paradigm to define a random measure (the posterior) and see if this contracts to the distribution that generated the data, as the information in the data increases indefinitely, and at what rate.



The Bayesian Choice

Motivation

The Bayesian Choice

Outline

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

The Bayesian paradigm is an elegant and unified approach.

According to the complete class theorem (e.g. Le Cam, 1964) the set of all **limits of Bayes procedures** is sufficiently rich to dominate every statistical procedure.

Does it work in nonparametrics?

Frequentist study:

We use the Bayesian paradigm to define a random measure (the posterior) and see if this contracts to the distribution that generated the data, as the information in the data increases indefinitely, and at what rate.

In nonparametrics the prior matters.

There are good ones and bad ones.



Outline

Motivation

The Bayesian Choice

Outline

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

PART 1: Generalities

PART 2: Gaussian process priors

PART 3: Adaptation



Motivation

Generalities

Setting

Toy problem

Brownian

motion—density

Integrated Brownian

motion—density

Setting

Setting

Entropy

Rate theorem

Rate

theorem-refined

Examples of settings

Examples of priors

Gaussian priors

Gaussian

priors-settings

Gaussian priors-proof

Gaussian

priors-examples

Adaptation

Generalities



Setting

Motivation

Generalities

Setting

Toy problem

Brownian

motion—density

Integrated Brownian
motion—density

Setting

Setting

Entropy

Rate theorem

Rate

theorem-refined

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

For $n = 1, 2, \dots$

- $(\mathcal{X}^{(n)}, \mathcal{A}^{(n)}, P_\theta^{(n)} : \theta \in \Theta_n)$ experiment
- (Θ_n, d_n) metric space
- $X^{(n)}$ observation, law $P_{\theta_0}^{(n)}$

Given prior Π_n on Θ_n form posterior

$$\Pi_n(B|X^{(n)}) = \frac{\int_B p_\theta^{(n)}(X^{(n)}) d\Pi_n(\theta)}{\int_{\Theta_n} p_\theta^{(n)}(X^{(n)}) d\Pi_n(\theta)}$$



Setting

Motivation

Generalities

Setting

Toy problem

Brownian motion—density

Integrated Brownian motion—density

Setting

Setting

Entropy

Rate theorem

Rate theorem-refined

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

For $n = 1, 2, \dots$

- $(\mathcal{X}^{(n)}, \mathcal{A}^{(n)}, P_\theta^{(n)}: \theta \in \Theta_n)$ experiment
- (Θ_n, d_n) metric space
- $X^{(n)}$ observation, law $P_{\theta_0}^{(n)}$

Given prior Π_n on Θ_n form posterior

$$\Pi_n(B|X^{(n)}) = \frac{\int_B p_\theta^{(n)}(X^{(n)}) d\Pi_n(\theta)}{\int_{\Theta_n} p_\theta^{(n)}(X^{(n)}) d\Pi_n(\theta)}$$

Rate of contraction is at least ε_n if $\forall M_n \rightarrow \infty$

$$P_{\theta_0}^{(n)} \Pi_n(\theta \in \Theta_n: d_n(\theta, \theta_0) \geq M_n \varepsilon_n | X^{(n)}) \rightarrow 0$$



Toy problem

Motivation

Generalities

Setting

Toy problem

Brownian motion—density
Integrated Brownian motion—density

Setting

Setting

Entropy

Rate theorem

Rate

theorem-refined

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

- X_1, \dots, X_n i.i.d. density p_0 on $[0, 1]$
- $(W_x : x \in [0, 1])$ Brownian motion

Form prior on p :

$$x \mapsto \frac{e^{W_x}}{\int_0^1 e^{W_y} dy}$$



Toy problem

Motivation

Generalities

Setting

Toy problem

Brownian motion—density
Integrated Brownian motion—density

Setting

Setting

Entropy

Rate theorem

Rate

theorem-refined

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

- X_1, \dots, X_n i.i.d. density p_0 on $[0, 1]$
- $(W_x : x \in [0, 1])$ Brownian motion

Form prior on p :

$$x \mapsto \frac{e^{W_x}}{\int_0^1 e^{W_y} dy}$$

Find rate if $\log p_0 \in C^\alpha[0, 1]$



Brownian motion—density

Motivation

Generalities

Setting

Toy problem

Brownian
motion—density

Integrated Brownian
motion—density

Setting

Setting

Entropy

Rate theorem

Rate
theorem-refined

Examples of settings

Examples of priors

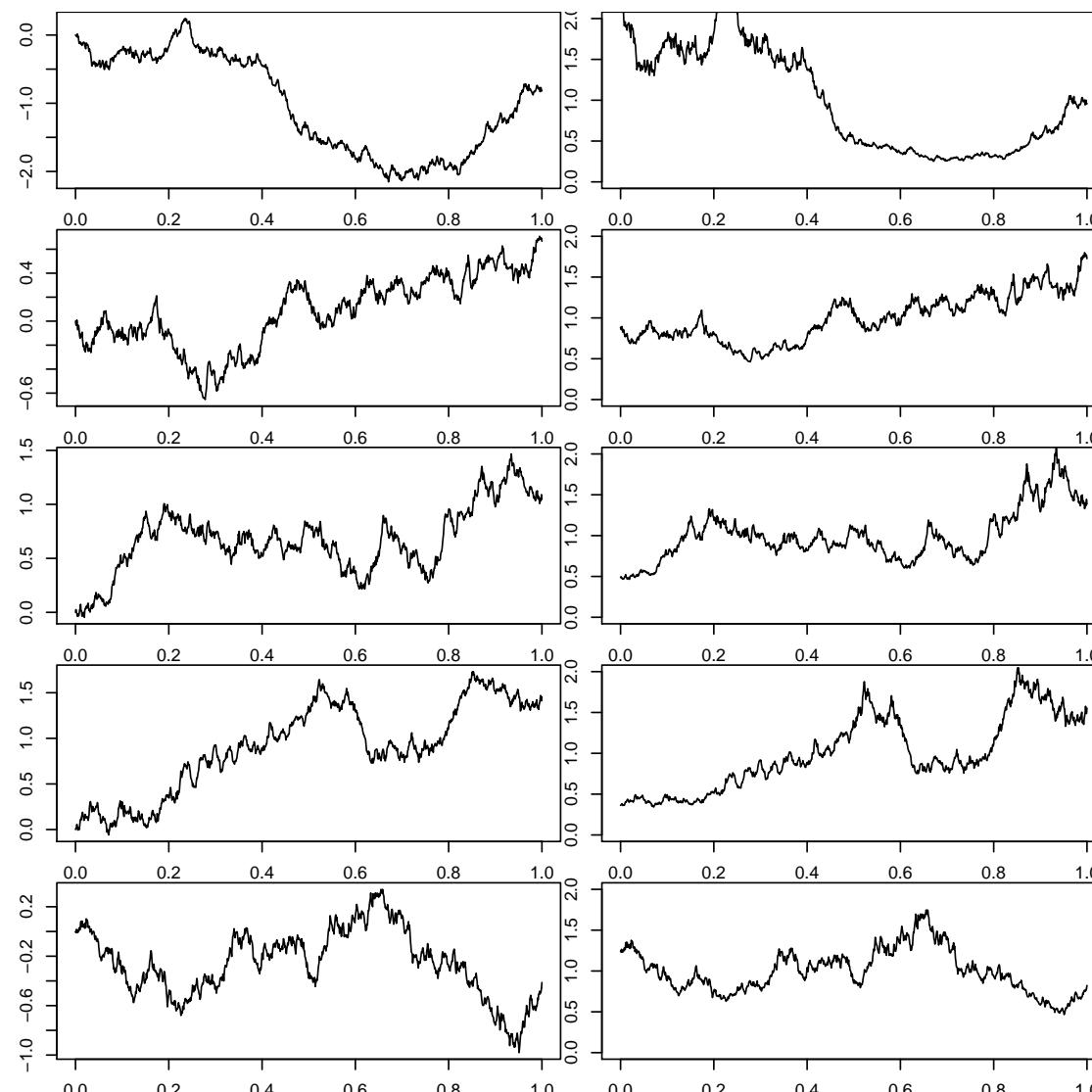
Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation





Integrated Brownian motion—density

Motivation

Generalities

Setting

Toy problem

Brownian
motion—density

Integrated Brownian
motion—density

Setting

Setting

Entropy

Rate theorem

Rate

theorem-refined

Examples of settings

Examples of priors

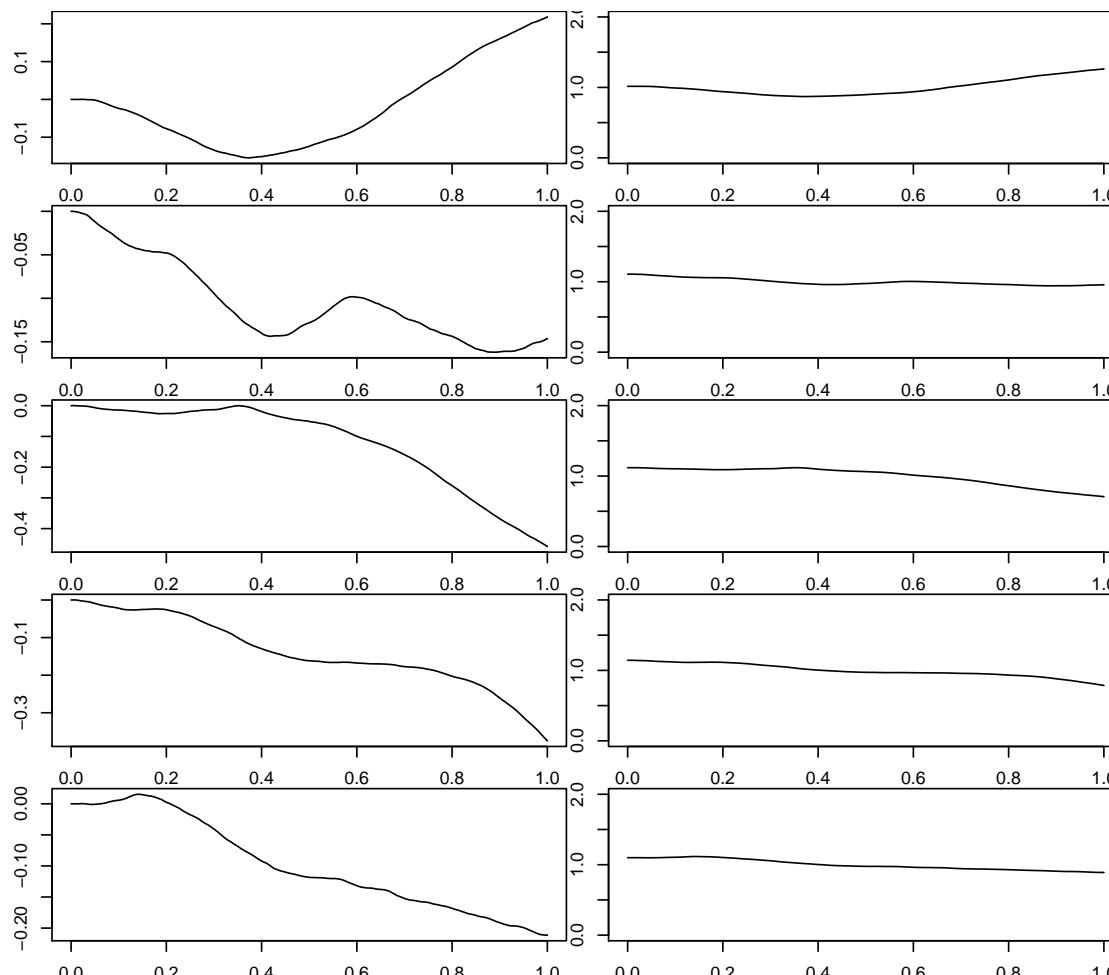
Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation





Setting

Motivation

Generalities

Setting

Toy problem

Brownian

motion—density

Integrated Brownian
motion—density

Setting

Setting

Entropy

Rate theorem

Rate

theorem-refined

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

For $n = 1, 2, \dots$

- $(\mathcal{X}^{(n)}, \mathcal{A}^{(n)}, P_\theta^{(n)}: \theta \in \Theta_n)$ experiment
- (Θ_n, d_n) metric space
- $X^{(n)}$ observation, law $P_{\theta_0}^{(n)}$

Given prior Π_n on Θ_n form posterior

$$\Pi_n(B|X^{(n)}) = \frac{\int_B p_\theta^{(n)}(X^{(n)}) d\Pi_n(\theta)}{\int_{\Theta_n} p_\theta^{(n)}(X^{(n)}) d\Pi_n(\theta)}$$

Rate of contraction is at least ε_n if $\forall M_n \rightarrow \infty$

$$P_{\theta_0}^{(n)} \Pi_n(\theta \in \Theta_n: d_n(\theta, \theta_0) \geq M_n \varepsilon_n | X^{(n)}) \rightarrow 0$$



Setting

Motivation

Generalities

Setting

Toy problem

Brownian motion—density

Integrated Brownian motion—density

Setting

Setting

Entropy

Rate theorem

Rate

theorem-refined

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

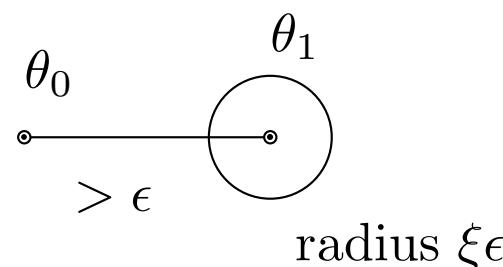
For $n = 1, 2, \dots$

- $(\mathcal{X}^{(n)}, \mathcal{A}^{(n)}, P_{\theta}^{(n)} : \theta \in \Theta_n)$ experiment
- (Θ_n, d_n) metric space
- $X^{(n)}$ observation, law $P_{\theta_0}^{(n)}$

Assume $\exists \xi > 0$ such that $\forall n \exists$ metric $\bar{d}_n \geq d_n$ such that $\forall \varepsilon > 0$:

$\forall \theta_1 \in \Theta_n$ with $d_n(\theta_1, \theta_0) > \varepsilon \exists$ test ϕ_n with

$$P_{\theta_0}^{(n)} \phi_n \leq e^{-n\varepsilon^2}, \quad \sup_{\theta \in \Theta_n : \bar{d}_n(\theta, \theta_1) < \varepsilon \xi} P_{\theta}^{(n)} (1 - \phi_n) \leq e^{-n\varepsilon^2}$$





Entropy

Motivation

Generalities

Setting

Toy problem

Brownian motion—density

Integrated Brownian motion—density

Setting

Setting

Entropy

Rate theorem

Rate

theorem-refined

Examples of settings

Examples of priors

Gaussian priors

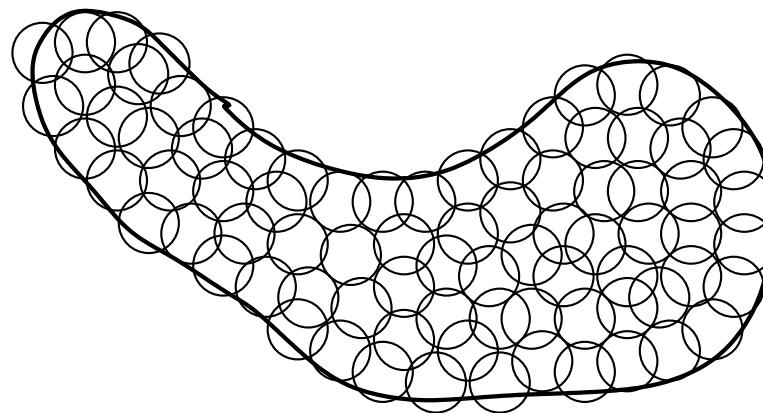
Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

$N(\varepsilon, \Theta, d) = \text{smallest number of balls of radius } \varepsilon \text{ needed to cover } \Theta$



Le Cam 73,75,86, Birgé 83, 06:

\exists estimators $\hat{\theta}_n$ with $d_n(\hat{\theta}_n, \theta_0) = O_P(\varepsilon_n)$ if

$$\sup_{\varepsilon > \varepsilon_n} \log N(\varepsilon \xi, \{\theta \in \Theta_n : d_n(\theta, \theta_0) \leq \varepsilon\}, \bar{d}_n) \leq n \varepsilon_n^2$$



Entropy

Motivation

Generalities

Setting

Toy problem

Brownian motion—density

Integrated Brownian motion—density

Setting

Setting

Entropy

Rate theorem

Rate

theorem-refined

Examples of settings

Examples of priors

Gaussian priors

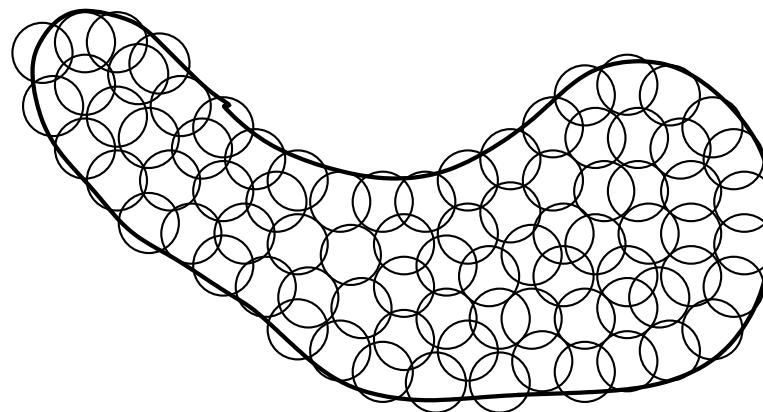
Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

$N(\varepsilon, \Theta, d) = \text{smallest number of balls of radius } \varepsilon \text{ needed to cover } \Theta$



Le Cam 73,75,86, Birgé 83, 06:

\exists estimators $\hat{\theta}_n$ with $d_n(\hat{\theta}_n, \theta_0) = O_P(\varepsilon_n)$ if

$$\log N(\varepsilon_n \xi, \Theta_n, \bar{d}_n) \leq n \varepsilon_n^2$$

If many balls are needed, then rate ε_n is slow



Rate theorem

Motivation

Generalities

Setting

Toy problem

Brownian

motion—density

Integrated Brownian

motion—density

Setting

Setting

Entropy

Rate theorem

Rate

theorem-refined

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

THEOREM (Ghosal & vdV, 2006)

For $\varepsilon_n \rightarrow 0$, $\varepsilon_n \gg 1/\sqrt{n}$, assume $\exists \tilde{\Theta}_n \subset \Theta_n$:

- $\log N(\varepsilon_n, \tilde{\Theta}_n, \bar{d}_n) \leq n\varepsilon_n^2$ entropy
- $\Pi_n(\tilde{\Theta}_n - \Theta_n) = o(e^{-3n\varepsilon_n^2})$
- $\Pi_n(B_n(\theta_0, \varepsilon_n; k)) \geq e^{-n\varepsilon_n^2}$ prior mass

Then $P_{\theta_0}^{(n)} \Pi_n(\theta \in \Theta_n: d_n(\theta, \theta_0) \geq M_n \varepsilon_n | X^{(n)}) \rightarrow 0$

$$B_n(\theta_0, \varepsilon; k) =$$

$$\left\{ \theta \in \Theta_n : K(p_{\theta_0}^{(n)}, p_\theta^{(n)}) \leq n\varepsilon^2, V_k(p_{\theta_0}^{(n)}, p_\theta^{(n)}) \leq n^{k/2} \varepsilon^k \right\}$$

(Kullback-Leibler neighborhood)

$$K(p, q) = P \log(p/q) \quad V_k(p, q) = P |\log(p/q) - K(p, q)|^k$$



Rate theorem-refined

Motivation

Generalities

Setting

Toy problem

Brownian motion—density

Integrated Brownian motion—density

Setting

Setting

Entropy

Rate theorem

Rate theorem-refined

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

THEOREM (Ghosal & vdV, 2006)

For $\varepsilon_n \rightarrow 0$, assume $\exists \tilde{\Theta}_n \subset \Theta_n$:

- $\sup_{\varepsilon > \varepsilon_n} \log N(\varepsilon \xi, \{\theta \in \tilde{\Theta}_n : d_n(\theta, \theta_0) < \varepsilon\}, \bar{d}_n) \leq n \varepsilon_n^2$
- $\frac{\Pi_n(\tilde{\Theta}_n - \Theta_n)}{\Pi_n(B_n(\theta_0, \varepsilon_n; k))} = o(e^{-2n\varepsilon_n^2})$
- $\frac{\Pi_n(\theta \in \Theta_n : d_n(\theta, \theta_0) \leq 2j\varepsilon_n)}{\Pi_n(B_n(\theta_0, \varepsilon_n; k))} \leq e^{Kn\varepsilon_n^2 j^2/2} \quad \forall j$

Then $P_{\theta_0}^{(n)} \Pi_n(\theta \in \Theta_n : d_n(\theta, \theta_0) \geq M_n \varepsilon_n | X^{(n)}) \rightarrow 0$



Motivation

Generalities

Examples of settings

I.i.d. observations

Independent
observations

Markov chains
Gaussian white noise
model

Gaussian time series

Ergodic diffusions

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

Examples of settings



I.i.d. observations

Motivation

Generalities

Examples of settings

I.i.d. observations

Independent observations

Markov chains

Gaussian white noise model

Gaussian time series

Ergodic diffusions

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

Data X_1, \dots, X_n , i.i.d. with density p_θ

MAIN RESULT HOLDS WITH

- d_n Hellinger distance h (or L_1 or L_2)
- $B_n(\theta_0, \varepsilon; 2) = \{\theta : K(\theta_0, \theta) \leq \varepsilon^2, V_2(\theta_0, \theta) \leq \varepsilon^2\}$

$$h(\theta, \theta')^2 = \int (\sqrt{p_\theta} - \sqrt{p_{\theta'}})^2 d\mu$$

$$K(\theta, \theta') = P_\theta \log(p_\theta / p_{\theta'})$$

$$V_2(\theta, \theta') = P_\theta (\log(p_\theta / p_{\theta'}))^2$$



Independent observations

Motivation

Generalities

Examples of settings

I.i.d. observations

Independent observations

Markov chains

Gaussian white noise model

Gaussian time series

Ergodic diffusions

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

Data X_1, \dots, X_n , independent with $X_i \sim p_{\theta,i}$

MAIN RESULT HOLDS WITH

- $d_n^2(\theta, \theta') = \frac{1}{n} \sum_{i=1}^n h_i(\theta, \theta')^2$
- $B_n(\theta_0, \varepsilon; 2) = \{\theta : \frac{1}{n} \sum_{i=1}^n K_i(\theta_0, \theta) \vee \frac{1}{n} \sum_{i=1}^n V_{2,i}(\theta_0, \theta) \leq \varepsilon^2\}$

h_i , K_i and $V_{2,i}$ computed for i th observation



Markov chains

Motivation

Generalities

Examples of settings

I.i.d. observations

Independent observations

Markov chains

Gaussian white noise model

Gaussian time series

Ergodic diffusions

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

Data (X_0, X_1, \dots, X_n) for $\dots, X_0, X_1, X_2, \dots$ stationary Markov chain with initial density q_θ and transition density $p_\theta(\cdot|\cdot)$

Assume \exists integrable r , constants $0 < c < C$ and $k > 2$:

1. $cr(y) \leq p_\theta(y|x) \leq Cr(y),$
2. $\alpha\text{-mixing}, \sum_{h=0}^{\infty} \alpha_h^{1-1/k} < \infty$

MAIN RESULT HOLDS WITH

- $d_n^2(\theta, \theta') = \iint \left[\sqrt{p_\theta(y|x)} - \sqrt{p_{\theta'}(y|x)} \right]^2 d\mu(y) r(x) d\mu(x)$
- $B_n(\theta_0, \varepsilon; k) = \left\{ \theta : P_{\theta_0} \log \frac{p_{\theta_0}}{p_\theta}(X_1|X_0) \leq \varepsilon^2, P_{\theta_0} \left| \log \frac{p_{\theta_0}}{p_\theta}(X_1|X_0) \right|^k \leq \varepsilon^k \right\}$



Gaussian white noise model

Motivation

Generalities

Examples of settings

I.i.d. observations

Independent observations

Markov chains

Gaussian white noise model

Gaussian time series

Ergodic diffusions

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

Data $(X_t^{(n)} : 0 \leq t \leq 1)$ for $dX_t^{(n)} = \theta(t) dt + n^{-1/2} dB_t$, where B is Brownian motion

MAIN RESULT HOLDS WITH

- d_n : L_2 -norm
- $B_n(\theta_0, \varepsilon; 2)$: L_2 -ball



Gaussian time series

Motivation

Generalities

Examples of settings

I.i.d. observations

Independent observations

Markov chains
Gaussian white noise model

Gaussian time series

Ergodic diffusions

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

Data (X_0, X_1, \dots, X_n) for $\dots, X_0, X_1, X_2, \dots$ stationary mean zero Gaussian process with spectral density $\theta \in \Theta$

Assume

1. $\sup_{\theta \in \Theta} \|\log \theta\|_\infty < \infty$
2. $\sup_{\theta \in \Theta} \sum_{h=-\infty}^{\infty} |h| (\mathbb{E}_\theta X_h X_0)^2 < \infty$

MAIN RESULT HOLDS WITH

- d_n : L_2 -norm, \bar{d}_n : supremum-norm
- $B_n(\theta_0, \varepsilon; 2)$: L_2 -ball



Ergodic diffusions

Motivation

Generalities

Examples of settings

I.i.d. observations

Independent observations

Markov chains

Gaussian white noise model

Gaussian time series

Ergodic diffusions

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

Data $(X_t: 0 \leq t \leq n)$ for X solution to

$dX_t = \theta(X_t) dt + \sigma(X_t) dB_t$, where B is Brownian motion B

Assume

1. stationary ergodic, state space I ,
2. stationary measure μ_{θ_0}

MAIN RESULT HOLDS WITH

- $d(\theta, \theta') = \|(\theta - \theta')1_J/\sigma\|_{\mu_{\theta_0}, 2} \quad J \subset I$
- $e(\theta, \theta') = \|(\theta - \theta')/\sigma\|_{\mu_{\theta_0}, 2}$
- $B(\theta_0, \varepsilon; 2) \|\cdot/\sigma\|_{\mu_{\theta_0}, 2}\text{-ball}$



Motivation

Generalities

Examples of settings

Examples of priors

Priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

Examples of priors



Priors

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

Priors

[Gaussian priors](#)

[Gaussian priors-settings](#)

[Gaussian priors-proof](#)

[Gaussian priors-examples](#)

[Adaptation](#)

Uniform priors on ε_n -nets



Priors

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

Priors

[Gaussian priors](#)

[Gaussian priors-settings](#)

[Gaussian priors-proof](#)

[Gaussian priors-examples](#)

[Adaptation](#)

Uniform priors on ε_n -nets

Smooth Euclidean prior on the parameters in a finite-dimensional approximation (e.g. series approximation, finite mixture density)



Priors

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

Priors

[Gaussian priors](#)

[Gaussian priors-settings](#)

[Gaussian priors-proof](#)

[Gaussian priors-examples](#)

[Adaptation](#)

Uniform priors on ε_n -nets

Smooth Euclidean prior on the parameters in a finite-dimensional approximation (e.g. series approximation, finite mixture density)

Random measures, such as Ferguson's Dirichlet or Polya trees



Priors

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

Priors

[Gaussian priors](#)

[Gaussian priors-settings](#)

[Gaussian priors-proof](#)

[Gaussian priors-examples](#)

[Adaptation](#)

Uniform priors on ε_n -nets

Smooth Euclidean prior on the parameters in a finite-dimensional approximation (e.g. series approximation, finite mixture density)

Random measures, such as Ferguson's Dirichlet or Polya trees

A stochastic process as model for a function, e.g. a Gaussian process or a Lévy process



Priors

Motivation

Generalities

Examples of settings

Examples of priors

Priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Adaptation

Uniform priors on ε_n -nets

Smooth Euclidean prior on the parameters in a finite-dimensional approximation (e.g. series approximation, finite mixture density)

Random measures, such as Ferguson's Dirichlet or Polya trees

A stochastic process as model for a function, e.g. a Gaussian process or a Lévy process

Combination of the previous as building blocks, e.g. mixtures



Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Setting

Reproducing kernel

Hilbert space

Small ball probability

Concentration
function

Main result

Toy
problem-Brownian
motion

Toy
problem-Brownian
motion

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

Gaussian priors



Setting

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Setting

Reproducing kernel

Hilbert space

Small ball probability

Concentration
function

Main result

Toy
problem-Brownian
motion

Toy
problem-Brownian
motion

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

Data $X^{(n)}$ follows density $p_{w_0}^{(n)}$ indexed by a function $w_0: T \rightarrow \mathbb{R}$

Prior Π_n for w is law of Gaussian process $(W_t: t \in T)$

Form posterior as before

$$\Pi_n(B|X^{(n)}) := \frac{\int_B p_w^{(n)}(X^{(n)}) d\Pi_n(w)}{\int p_w^{(n)}(X^{(n)}) d\Pi_n(w)}$$



Setting

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Setting

Reproducing kernel

Hilbert space

Small ball probability

Concentration
function

Main result

Toy
problem-Brownian
motion

Toy
problem-Brownian
motion

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

Data $X^{(n)}$ follows density $p_{w_0}^{(n)}$ indexed by a function $w_0: T \rightarrow \mathbb{R}$

Prior Π_n for w is law of Gaussian process $(W_t: t \in T)$

Form posterior as before

$$\Pi_n(B|X^{(n)}):= \frac{\int_B p_w^{(n)}(X^{(n)}) d\Pi_n(w)}{\int p_w^{(n)}(X^{(n)}) d\Pi_n(w)}$$

Rate of contraction is at least ε_n if $\forall M_n \rightarrow \infty$

$$P_{w_0}^{(n)} \Pi_n(w: d_n(w, w_0) \geq M_n \varepsilon_n | X^{(n)}) \rightarrow 0$$



Reproducing kernel Hilbert space

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

Setting

Reproducing kernel
Hilbert space

Small ball probability

Concentration
function

Main result

Toy
problem-Brownian
motion

Toy
problem-Brownian
motion

Gaussian
priors-settings

[Gaussian priors-proof](#)

[Gaussian
priors-examples](#)

[Adaptation](#)

To every Gaussian random element with values in a Banach space $(\mathbb{B}, \|\cdot\|)$ is attached a certain Hilbert space $(\mathbb{H}, \|\cdot\|_{\mathbb{H}})$, called the RKHS



Reproducing kernel Hilbert space

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

Setting

Reproducing kernel
Hilbert space

Small ball probability

Concentration
function

Main result

Toy
problem-Brownian
motion

Toy
problem-Brownian
motion

Gaussian
priors-settings

[Gaussian priors-proof](#)

[Gaussian
priors-examples](#)

[Adaptation](#)

To every Gaussian random element with values in a Banach space $(\mathbb{B}, \|\cdot\|)$ is attached a certain Hilbert space $(\mathbb{H}, \|\cdot\|_{\mathbb{H}})$, called the RKHS

$\|\cdot\|_{\mathbb{H}}$ is stronger than $\|\cdot\|$ and can view $\mathbb{H} \subset \mathbb{B}$



Reproducing kernel Hilbert space

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

Setting

Reproducing kernel
Hilbert space

Small ball probability

Concentration
function

Main result

Toy
problem-Brownian
motion

Toy
problem-Brownian
motion

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

To every Gaussian random element with values in a Banach space $(\mathbb{B}, \|\cdot\|)$ is attached a certain Hilbert space $(\mathbb{H}, \|\cdot\|_{\mathbb{H}})$, called the RKHS

$\|\cdot\|_{\mathbb{H}}$ is stronger than $\|\cdot\|$ and can view $\mathbb{H} \subset \mathbb{B}$

EXAMPLE

The RKHS of Brownian motion as map in $C[0, 1]$ is

$\mathbb{H} = \{h: \int h'(t)^2 dt < \infty\}$ with norm $\|h\|_{\mathbb{H}} = \|h'\|_2$



Small ball probability

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

Setting

Reproducing kernel

Hilbert space

Small ball probability

Concentration
function

Main result

Toy
problem-Brownian
motion

Toy
problem-Brownian
motion

Gaussian
priors-settings

[Gaussian priors-proof](#)

Gaussian
priors-examples

[Adaptation](#)

W Gaussian map in $(\mathbb{B}, \|\cdot\|)$

$$\mathbb{P}(\|W\| < \varepsilon) = e^{-\phi_0(\varepsilon)}$$



Small ball probability

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Setting

Reproducing kernel

Hilbert space

Small ball probability

Concentration
function

Main result

Toy
problem-Brownian
motion

Toy
problem-Brownian
motion

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

W Gaussian map in $(\mathbb{B}, \|\cdot\|)$

$$P(\|W\| < \varepsilon) = e^{-\phi_0(\varepsilon)}$$

Small ball probability can be computed for many examples,
either by probabilistic arguments, or by using:

THEOREM (Kuelbs and Li, 1993)

$$\phi_0(\varepsilon) \asymp \log N(\varepsilon / \sqrt{\phi_0(\varepsilon)}, \mathbb{H}_1, \|\cdot\|)$$

for \mathbb{H}_1 the unit ball of the RKHS

up to factors of 2 and regularity



Concentration function

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

Setting

Reproducing kernel

Hilbert space

Small ball probability

Concentration
function

Main result

Toy

problem-Brownian
motion

Toy

problem-Brownian
motion

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

W Gaussian map in $(\mathbb{B}, \|\cdot\|)$ with RKHS $(\mathbb{H}, \|\cdot\|_{\mathbb{H}})$

$$P(\|W\| < \varepsilon) = e^{-\phi_0(\varepsilon)}$$

$$\phi_{w_0}(\varepsilon) := \phi_0(\varepsilon) + \inf_{h \in \mathbb{H}: \|h - w_0\| < \varepsilon} \|h\|_{\mathbb{H}}^2$$



Concentration function

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Setting

Reproducing kernel

Hilbert space

Small ball probability

Concentration
function

Main result

Toy

problem-Brownian
motion

Toy
problem-Brownian
motion

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

W Gaussian map in $(\mathbb{B}, \|\cdot\|)$ with RKHS $(\mathbb{H}, \|\cdot\|_{\mathbb{H}})$

$$P(\|W\| < \varepsilon) = e^{-\phi_0(\varepsilon)}$$

$$\phi_{w_0}(\varepsilon) := \phi_0(\varepsilon) + \inf_{h \in \mathbb{H}: \|h - w_0\| < \varepsilon} \|h\|_{\mathbb{H}}^2$$

THEOREM (Kuelbs and Li, 1993)

Concentration function measures concentration around w_0 :

$$P(\|W - w_0\| < \varepsilon) \asymp e^{-\phi_{w_0}(\varepsilon)}$$

up to factors 2



Main result

1

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Setting

Reproducing kernel

Hilbert space

Small ball probability

Concentration

function

Main result

Toy

problem-Brownian

motion

Toy

problem-Brownian

motion

Gaussian

priors-settings

Gaussian priors-proof

Gaussian

priors-examples

Adaptation

W Gaussian map in $(\mathbb{B}, \|\cdot\|)$, RKHS $(\mathbb{H}, \|\cdot\|_{\mathbb{H}})$

$$P(\|W\| < \varepsilon) = e^{-\phi_0(\varepsilon)}$$

Assume that various distances on the model combine “appropriately” with the norm $\|\cdot\|$ on W (see below) and that $\varepsilon_n \gg 1/\sqrt{n}$

THEOREM

Posterior rate is ε_n if $\phi_{w_0}(\varepsilon_n) \leq n\varepsilon_n^2$, i.e. if

$$\phi_0(\varepsilon_n) \leq n\varepsilon_n^2 \quad \text{AND} \quad \inf_{h \in \mathbb{H}: \|h - w_0\| < \varepsilon_n} \|h\|_{\mathbb{H}}^2 \leq n\varepsilon_n^2$$

First depends on W and not on w_0



Toy problem-Brownian motion

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Setting

Reproducing kernel

Hilbert space

Small ball probability

Concentration

function

Main result

Toy
problem-Brownian
motion

Toy
problem-Brownian
motion

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

W one-dimensional Brownian motion on $[0, 1]$

Intuition

Support is full space (if started at random)

Sample paths are $1/2$ -smooth

So BM is appropriate prior if $w_0 \in C^\alpha[0, 1]$ for $\alpha = 1/2$

If w_0 smoother than $1/2$: BM too spread out

If w_0 coarser than $1/2$: BM too smooth to be close

In fact: rate is $n^{-1/4}$ if $\alpha \geq 1/2$; $n^{-\alpha/2}$ if $\alpha \leq 1/2$

This is optimal if and only if $\alpha = 1/2$



Toy problem-Brownian motion

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Setting

Reproducing kernel

Hilbert space

Small ball probability

Concentration

function

Main result

Toy

problem-Brownian

motion

Toy
problem-Brownian
motion

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

W one-dimensional Brownian motion on $[0, 1]$

Mathematics

Small ball probability $\phi_0(\varepsilon) \asymp (1/\varepsilon)^2$

RKHS $\mathbb{H} = \{h: \int h'(t)^2 dt < \infty\}$, $\|h\|_{\mathbb{H}} = \|h'\|_2$

LEMMA

If $w_0 \in C^\alpha[0, 1]$ for $0 < \alpha < 1$, then

$$\inf_{h \in \mathbb{H}: \|h - w_0\|_\infty < \varepsilon} \|h\|_{\mathbb{H}}^2 \asymp (1/\varepsilon)^{(2-2\alpha)/\alpha}$$



Toy problem-Brownian motion

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Setting

Reproducing kernel

Hilbert space

Small ball probability

Concentration

function

Main result

Toy

problem-Brownian

motion

Toy
problem-Brownian
motion

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

W one-dimensional Brownian motion on $[0, 1]$

Mathematics

Small ball probability $\phi_0(\varepsilon) \asymp (1/\varepsilon)^2$

RKHS $\mathbb{H} = \{h: \int h'(t)^2 dt < \infty\}$, $\|h\|_{\mathbb{H}} = \|h'\|_2$

LEMMA

If $w_0 \in C^\alpha[0, 1]$ for $0 < \alpha < 1$, then

$$\inf_{h \in \mathbb{H}: \|h - w_0\|_\infty < \varepsilon} \|h\|_{\mathbb{H}}^2 \asymp (1/\varepsilon)^{(2-2\alpha)/\alpha}$$

CONSEQUENCE:

Rate is ε_n if

$$(1/\varepsilon_n)^2 \leq n\varepsilon_n^2 \text{ AND } (1/\varepsilon_n)^{(2-2\alpha)/\alpha} \leq n\varepsilon_n^2$$

First implies $\varepsilon_n \geq n^{-1/4}$ for any w_0 .

Second implies $\varepsilon_n \geq n^{-\alpha/2}$ for $w_0 \in C^\alpha[0, 1]$



Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Main
result-remember

Density estimation

Classification

Regression

Gaussian white noise

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

Gaussian priors-settings



Main result-remember

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

[Gaussian priors-settings](#)

Main result-remember

Density estimation

Classification

Regression

Gaussian white noise

[Gaussian priors-proof](#)

[Gaussian priors-examples](#)

[Adaptation](#)

W Gaussian map in $(\mathbb{B}, \|\cdot\|)$, RKHS $(\mathbb{H}, \|\cdot\|_{\mathbb{H}})$

$$P(\|W\| < \varepsilon) = e^{-\phi_0(\varepsilon)}$$

Assume that various distances on the model combine “appropriately” with the norm $\|\cdot\|$ on W (see below) and that $\varepsilon_n \gg 1/\sqrt{n}$

THEOREM

Posterior rate is ε_n if $\phi_{w_0}(\varepsilon_n) \leq n\varepsilon_n^2$, i.e.

$$\inf_{h \in \mathbb{H}: \|h - w_0\| < \varepsilon_n} \|h\|_{\mathbb{H}}^2 \leq n\varepsilon_n^2 \quad \text{AND} \quad \phi_0(\varepsilon_n) \leq n\varepsilon_n^2$$



Density estimation

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Main
result-remember

Density estimation

Classification

Regression

Gaussian white noise

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

Data X_1, \dots, X_n i.i.d. from density on $[0, 1]$

$$p_w(x) = \frac{e^{w_x}}{\int_0^1 e^{w_t} dt}$$

- Distance on parameter: Hellinger distance on p_w
- Norm on W : uniform



Density estimation

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Main
result-remember

Density estimation

Classification

Regression

Gaussian white noise

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

Data X_1, \dots, X_n i.i.d. from density on $[0, 1]$

$$p_w(x) = \frac{e^{w_x}}{\int_0^1 e^{w_t} dt}$$

- Distance on parameter: Hellinger distance on p_w
- Norm on W : uniform

LEMMA

$\forall v, w$

- $h(p_v, p_w) \leq \|v - w\|_\infty e^{\|v-w\|_\infty/2}$
- $K(p_v, p_w) \lesssim \|v - w\|_\infty^2 e^{\|v-w\|_\infty} (1 + \|v - w\|_\infty)$
- $V(p_v, p_w) \lesssim \|v - w\|_\infty^2 e^{\|v-w\|_\infty} (1 + \|v - w\|_\infty)^2$



Classification

[Motivation](#)[Generalities](#)[Examples of settings](#)[Examples of priors](#)[Gaussian priors](#)[Gaussian priors-settings](#)

Main
result-remember
Density estimation

[Classification](#)

Regression
Gaussian white noise

[Gaussian priors-proof](#)[Gaussian priors-examples](#)[Adaptation](#)

Data $(X_1, Y_1), \dots, (X_n, Y_n)$ i.i.d. in $[0, 1] \times \{0, 1\}$

$$\Pr(Y = 1 | X = x) = \Psi(w_x)$$

E.g. Ψ logistic or probit link function

- Distance on parameter: L_2 -norm on $\Psi(w)$
- Norm on W for logistic: $L_2(G)$, G marginal of X_i
Norm on W for probit: combination of $L_2(G)$ and $L_4(G)$



Regression

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

[Gaussian priors-settings](#)

Main
result-remember

Density estimation

Classification

Regression

Gaussian white noise

[Gaussian priors-proof](#)

[Gaussian priors-examples](#)

[Adaptation](#)

Data Y_1, \dots, Y_n

$$Y_i = w_0(x_i) + e_i$$

x_1, \dots, x_n fixed design points

e_1, \dots, e_n i.i.d. Gaussian mean-zero errors

- Distance on parameter: empirical L_2 -distance on w
- Norm on W : uniform

Can use posterior for Gaussian errors also if errors have only mean zero? (Kleijn & vdV, 2006)



Gaussian white noise

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

[Gaussian priors-settings](#)

Main
result-remember

Density estimation

Classification

Regression

Gaussian white noise

[Gaussian priors-proof](#)

[Gaussian priors-examples](#)

[Adaptation](#)

Data ($X_t: t \in [0, 1]$)

$$dX_t = w_t + n^{-1/2} dB_t$$

- Distance on parameter: L_2
- Norm on W : L_2



Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Main
result-remember
Reproducing kernel
Hilbert
space-definition
Reproducing kernel
Hilbert
space-definition (2)

Geometry

Proof (1)

Proof (2)

Gaussian
priors-examples

Adaptation

Gaussian priors-proof



Main result-remember

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

[Gaussian priors-settings](#)

[Gaussian priors-proof](#)

**Main
result-remember**

Reproducing kernel

Hilbert
space-definition

Reproducing kernel
Hilbert
space-definition (2)

Geometry

Proof (1)

Proof (2)

[Gaussian
priors-examples](#)

[Adaptation](#)

W Gaussian map in $(\mathbb{B}, \|\cdot\|)$, RKHS $(\mathbb{H}, \|\cdot\|_{\mathbb{H}})$

$$P(\|W\| < \varepsilon) = e^{-\phi_0(\varepsilon)}$$

Assume that various distances on the model combine “appropriately” with the norm $\|\cdot\|$ on W (see below) and that $\varepsilon_n \gg 1/\sqrt{n}$

THEOREM

Posterior rate is ε_n if $\phi_{w_0}(\varepsilon_n) \leq n\varepsilon_n^2$, i.e.

$$\inf_{h \in \mathbb{H}: \|h - w_0\| < \varepsilon_n} \|h\|_{\mathbb{H}}^2 \leq n\varepsilon_n^2 \quad \text{AND} \quad \phi_0(\varepsilon_n) \leq n\varepsilon_n^2$$



Reproducing kernel Hilbert space-definition

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Main
result-remember
Reproducing kernel
Hilbert
space-definition

Reproducing kernel
Hilbert
space-definition (2)

Geometry
Proof (1)
Proof (2)

Gaussian priors-examples

Adaptation

W zero-mean Gaussian in $(\mathbb{B}, \|\cdot\|)$

$$S: \mathbb{B}^* \rightarrow \mathbb{B}, \quad Sb^* = E W b^*(W)$$

RKHS $(\mathbb{H}, \|\cdot\|_{\mathbb{H}})$ is the completion of $S\mathbb{B}^*$ under

$$\langle Sb_1^*, Sb_2^* \rangle_{\mathbb{H}} = E b_1^*(W) b_2^*(W)$$



Reproducing kernel Hilbert space-definition (2)

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

[Gaussian priors-settings](#)

[Gaussian priors-proof](#)

Main
result-remember
Reproducing kernel
Hilbert
space-definition

Reproducing kernel
Hilbert
space-definition (2)

Geometry

Proof (1)

Proof (2)

Gaussian
priors-examples

Adaptation

$W = (W_x: x \in \mathcal{X})$ Gaussian stochastic process which can be seen as tight, Borel measurable map in $\ell^\infty(\mathcal{X}) = \{f: \mathcal{X} \rightarrow \mathbb{R}: \sup_x |f(x)| < \infty\}$

Covariance function $K(x, y) = \mathbb{E}W_x W_y$

Then RKHS is completion of the set of functions

$x \mapsto \sum_i \alpha_i K(y_i, x)$

relative to inner product

$$\left\langle \sum_i \alpha_i K(y_i, \cdot), \sum_j \beta_j K(z_j, \cdot) \right\rangle_{\mathbb{H}} = \sum_i \sum_j \alpha_i \beta_j K(y_i, z_j)$$



Geometry

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Main

result-remember

Reproducing kernel

Hilbert

space-definition

Reproducing kernel

Hilbert

space-definition (2)

Geometry

Proof (1)

Proof (2)

Gaussian priors-examples

Adaptation

RKHS gives the “geometry” of the support of W

THEOREM

Norm closure of \mathbb{H} in \mathbb{B} is smallest closed set with probability one under Gaussian measure



Geometry

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

[Gaussian priors-settings](#)

[Gaussian priors-proof](#)

Main

result-remember

Reproducing kernel

Hilbert

space-definition

Reproducing kernel

Hilbert

space-definition (2)

Geometry

Proof (1)

Proof (2)

[Gaussian](#)

[priors-examples](#)

[Adaptation](#)

RKHS gives the “geometry” of the support of W

THEOREM

Norm closure of \mathbb{H} in \mathbb{B} is smallest closed set with probability one under Gaussian measure

CONSEQUENCE: posterior inconsistent if $\|w_0 - \mathbb{H}\| > 0$



Geometry

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Main
result-remember
Reproducing kernel
Hilbert
space-definition
Reproducing kernel
Hilbert
space-definition (2)

Geometry

Proof (1)

Proof (2)

Gaussian
priors-examples

Adaptation

RKHS gives the “geometry” of the support of W

THEOREM

Norm closure of \mathbb{H} in \mathbb{B} is smallest closed set with probability one under Gaussian measure

THEOREM (Kuelbs & Li, 1993)

For $N(\varepsilon, \mathbb{H}_1, \|\cdot\|)$ minimal number of balls needed to cover unit ball of RKHS:

$$\phi_0(\varepsilon) \asymp \log N(\varepsilon / \sqrt{\phi_0(\varepsilon)}, \mathbb{H}_1, \|\cdot\|)$$



Geometry

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Main
result-remember
Reproducing kernel
Hilbert
space-definition
Reproducing kernel
Hilbert
space-definition (2)

Geometry

Proof (1)

Proof (2)

Gaussian
priors-examples

Adaptation

RKHS gives the “geometry” of the support of W

THEOREM

Norm closure of \mathbb{H} in \mathbb{B} is smallest closed set with probability one under Gaussian measure

THEOREM (Kuelbs & Li, 1993)

For $N(\varepsilon, \mathbb{H}_1, \|\cdot\|)$ minimal number of balls needed to cover unit ball of RKHS:

$$\phi_0(\varepsilon) \asymp \log N(\varepsilon / \sqrt{\phi_0(\varepsilon)}, \mathbb{H}_1, \|\cdot\|)$$

THEOREM (Borell, 1975)

$$P(W \notin \varepsilon \mathbb{B}_1 + M \mathbb{H}_1) \leq 1 - \Phi(\Phi^{-1}(e^{-\phi_0(\varepsilon)}) + M)$$



Proof (1)

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Main

result-remember

Reproducing kernel

Hilbert

space-definition

Reproducing kernel

Hilbert

space-definition (2)

Geometry

Proof (1)

Proof (2)

Gaussian priors-examples

Adaptation

Sufficient for posterior rate of ε_n is existence of sets \mathbb{B}_n with

- $\log N(\varepsilon_n, \mathbb{B}_n, d_n) \leq n\varepsilon_n^2$ entropy
- $\Pi_n(\mathbb{B}_n) = 1 - o(e^{-3n\varepsilon_n^2})$
- $\Pi_n(B_n(w_0, \varepsilon_n)) \geq e^{-n\varepsilon_n^2}$ prior mass

$B_n(w_0, \varepsilon)$ is Kullback-Leibler neighborhood of $P_{w_0}^{(n)}$
(Ghosal & vdV, 2000, 2006)



Proof (2)

- [Motivation](#)
- [Generalities](#)
- [Examples of settings](#)
- [Examples of priors](#)
- [Gaussian priors](#)
- [Gaussian priors-settings](#)
- [Gaussian priors-proof](#)
 - Main
 - result-remember
 - Reproducing kernel Hilbert space-definition
 - Reproducing kernel Hilbert space-definition (2)
 - Geometry
 - Proof (1)
 - Proof (2)**
- [Gaussian priors-examples](#)
- [Adaptation](#)

W Gaussian map in $(\mathbb{B}, \|\cdot\|)$, RKHS $(\mathbb{H}, \|\cdot\|_{\mathbb{H}})$
 $P(\|W\| < \varepsilon) = e^{-\phi_0(\varepsilon)}$

THEOREM

$\forall w_0 \in \overline{\mathbb{H}}$ and $\varepsilon_n > 0$ with

$$\inf_{h \in \mathbb{H}: \|h - w_0\| < \varepsilon_n} \|h\|_{\mathbb{H}}^2 + \phi_0(\varepsilon_n) \leq n\varepsilon_n^2$$

$\exists \mathbb{B}_n \subset \mathbb{B}$ with

- $\log N(\varepsilon_n, \mathbb{B}_n, \|\cdot\|) \lesssim n\varepsilon_n^2$
- $P(W \notin \mathbb{B}_n) \lesssim e^{-4n\varepsilon_n^2}$
- $P(\|W - w_0\| < \varepsilon_n) \gtrsim e^{-n\varepsilon_n^2}$

PROOF

Take $\mathbb{B}_n = M_n \mathbb{H}_1 + \varepsilon_n \mathbb{B}_1$ for appropriate M_n
Use Borell's inequality



Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

**Gaussian
priors-examples**

Brownian motion

Integrated Brownian motion

Spline smoothing in regression

Riemann-Liouville process

Fractional Brownian motion

Expansions

Rescaled Brownian motion

Rescaled integrated Brownian motion

Rescaled stationary process

Gaussian priors-examples



Brownian motion

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

[Gaussian priors-settings](#)

[Gaussian priors-proof](#)

[Gaussian priors-examples](#)

[Brownian motion](#)

Integrated Brownian motion

Spline smoothing in regression

Riemann-Liouville process

Fractional Brownian motion

Expansions

Rescaled Brownian motion

Rescaled integrated Brownian motion

Rescaled stationary process

W one-dimensional Brownian motion on $[0, 1]$

BM is appropriate prior if truth is $1/2$ -smooth

If truth smoother than $1/2$: BM too spread out

If truth coarser than $1/2$: BM too smooth to be close

In both cases can obtain better rates with other priors

[Adaptation](#)



Integrated Brownian motion

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Brownian motion

Integrated Brownian motion

Spline smoothing in regression

Riemann-Liouville process

Fractional Brownian motion

Expansions

Rescaled Brownian motion

Rescaled integrated Brownian motion

Rescaled stationary process

Adaptation

Let I_{0+}^k denote k times integration from 0 and

$$W_t = (I_{0+}^k B)_t + \sum_{j=0}^k Z_j t^j$$

[B Brownian motion, (Z_j) iid $N(0, 1)$]

Gives appropriate model for $k + 1/2$ -smooth functions



Spline smoothing in regression

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Brownian motion
Integrated Brownian motion

Spline smoothing in regression

Riemann-Liouville process

Fractional Brownian motion

Expansions

Rescaled Brownian motion

Rescaled integrated Brownian motion

Rescaled stationary process

$$W_t = \sqrt{b}(I_{0+}^k B)_t + \sqrt{a} \sum_{j=0}^k Z_j t^j$$

If $a \rightarrow \infty$ and b, n are fixed, then the posterior mean tends to the minimizer of

$$w \mapsto \frac{1}{n} \sum_{i=1}^n (Y_i - w(x_i))^2 + \frac{\sigma^2}{nb} \int_0^1 w^{(k)}(t)^2 dt.$$

(Kimeldorf and Wahba, 1970, Wahba, 1978)

If $w_0 \in H^k[0, 1]$ and $\sigma^2/nb \sim n^{-2k/(2k+1)}$, i.e. $b \sim n^{-1/(2k+1)}$, the penalized least squares estimator is rate optimal



Riemann-Liouville process

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Brownian motion

Integrated Brownian motion

Spline smoothing in regression

Riemann-Liouville process

Fractional Brownian motion

Expansions

Rescaled Brownian motion

Rescaled integrated Brownian motion

Rescaled stationary process

$$W_t = \int_0^t (t-s)^{\alpha-1/2} dB_s + \sum_{k=0}^{[\alpha]+1} Z_k t^k$$

[B Brownian motion, $\alpha > 0$, (Z_k) iid $N(0, 1)$]

“Fractional integral”

Gives appropriate models for α -smooth functions



Fractional Brownian motion

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Brownian motion

Integrated Brownian motion

Spline smoothing in regression

Riemann-Liouville process

Fractional Brownian motion

Expansions

Rescaled Brownian motion

Rescaled integrated Brownian motion

Rescaled stationary process

Adaptation

W zero-mean Gaussian with

$$\text{cov}(W_s, W_t) = s^{2\alpha} + t^{2\alpha} - |t - s|^{2\alpha}$$

[Hurst index $0 < \alpha < 1$]

Gives appropriate model for α -smooth functions

Can integrate this to cover $\alpha > 1$



Expansions

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Brownian motion

Integrated Brownian motion

Spline smoothing in regression

Riemann-Liouville process

Fractional Brownian motion

Expansions

Rescaled Brownian motion

Rescaled integrated Brownian motion

Rescaled stationary process

Infinite series

$$W_t = \sum_{i=1}^{\infty} \lambda_i Z_i e_i(t)$$

[(e_i) basis, (Z_i) i.i.d. $N(0, 1)$, $\lambda_i \rightarrow 0$]

[example: eigen expansion]

RKHS $\{\sum w_i e_i : \sum_i w_i / \lambda_i^2 < \infty\}$

Truncated series

$$W_t = \sum_{i=1}^N \mu_i Z_i e_i(t)$$

[(e_i) basis, (Z_i) i.i.d. $N(0, 1)$, $\mu_i \rightarrow 0$]

Appropriate (λ_i) or $N \rightarrow \infty$ and (μ_i) give proper models for α -smooth functions



Rescaled Brownian motion

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Brownian motion

Integrated Brownian motion

Spline smoothing in regression

Riemann-Liouville process

Fractional Brownian motion

Expansions

Rescaled Brownian motion

Rescaled integrated Brownian motion

Rescaled stationary process

Adaptation

$W_t = B_{t/c}$ for B Brownian motion, $t \in [0, 1]$ and
 $c \sim n^{(2\alpha-1)/(2\alpha+1)}$

$\alpha < 1/2$: $1/c \rightarrow \infty$ (shrink)

$\alpha \in (1/2, 1]$: $1/c \rightarrow 0$ (stretch)

Gives optimal rate for $w_0 \in C^\alpha[0, 1]$, any $\alpha \in (0, 1]$

Surprising? (Brownian motion is self-similar!)

“On infinitesimal intervals BM looks like a function in its RKHS”



Rescaled integrated Brownian motion

$$W_t = (I_{0+}^k B)_{t/c} + \sum_{j=0}^k Z_j t^j, \quad t \in [0, 1] \text{ and}$$
$$c \sim n^{(\alpha-k-1/2)/(2\alpha+1)(k+1/2)}$$

Gives optimal rate for $w_0 \in C^\alpha[0, 1]$, any $\alpha \in (0, k + 1]$

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Brownian motion

Integrated Brownian
motion

Spline smoothing in
regression

Riemann-Liouville
process

Fractional Brownian
motion

Expansions

Rescaled Brownian
motion

Rescaled integrated
Brownian motion

Rescaled stationary
process

Adaptation



Rescaled stationary process

Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian priors-settings

Gaussian priors-proof

Gaussian priors-examples

Brownian motion

Integrated Brownian motion

Spline smoothing in regression

Riemann-Liouville process

Fractional Brownian motion

Expansions

Rescaled Brownian motion

Rescaled integrated Brownian motion

Rescaled stationary process

$W_t = G_{t/c_n}$ for a centered Gaussian process G with

$$\mathbb{E}G_s G_t = \phi(s - t), \quad c_n = n^{1/(2\alpha+1)}$$

if $\int e^{\gamma t} \mathcal{F}\phi(t) dt < \infty$ for some $\gamma > 0$, then prior gives optimal rate for $w_0 \in C^\alpha[0, 1]$ up to a $\log n$ -factor, $\alpha > 0$

Adaptation



Motivation

Generalities

Examples of settings

Examples of priors

Gaussian priors

Gaussian
priors-settings

Gaussian priors-proof

Gaussian
priors-examples

Adaptation

Adaptation

Adaptation (1)

Adaptation (2)

Adaptation (3)

Adaptation



Adaptation

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

[Gaussian priors-settings](#)

[Gaussian priors-proof](#)

[Gaussian priors-examples](#)

[Adaptation](#)

[Adaptation](#)

[Adaptation \(1\)](#)

[Adaptation \(2\)](#)

[Adaptation \(3\)](#)

For every level of regularity α there is an optimal prior.

Construct an overall prior in two steps:

- Sample a regularity level α from a prior on $(0, \infty)$
- Given α , choose w from the prior that is optimal for α

The Bayesian machine will make the data choose the α that is appropriate for the data?



Adaptation (1)

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

[Gaussian priors-settings](#)

[Gaussian priors-proof](#)

[Gaussian priors-examples](#)

[Adaptation](#)

[Adaptation](#)

[Adaptation \(1\)](#)

[Adaptation \(2\)](#)

[Adaptation \(3\)](#)

For $n = 1, 2, \dots$ and every α in a arbitrary countable set A_n let $\Pi_{n,\alpha}$ a prior on a model $\mathcal{P}_{n,\alpha}$ and let $\varepsilon_{n,\alpha}$ a rate such that $\log N(\varepsilon_{n,\alpha}, \mathcal{P}_{n,\alpha}, d_n) \lesssim n\varepsilon_{n,\alpha}^2$

Let λ_n a probability measure on A_n such that

$$\lambda_n\{\alpha\} \propto \mu_\alpha e^{-Cn\varepsilon_{n,\alpha}^2}$$

THEOREM (Lember, vdV, 2005,2007)

If $\sum_\alpha \sqrt{\mu_\alpha} < \infty$ and $\sum_\alpha (\mu_\alpha / \mu_\beta) e^{-Cn\varepsilon_{n,\alpha}^2/4} = O(1)$, then the posterior rate is at least $\varepsilon_{n,\beta}$ for any β such that

$$\Pi_{n,\beta}(B_n(\varepsilon_{n,\beta})) \geq e^{-Fn\varepsilon_{n,\beta}^2}.$$



Adaptation (2)

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

[Gaussian priors-settings](#)

[Gaussian priors-proof](#)

[Gaussian priors-examples](#)

[Adaptation](#)

[Adaptation](#)

[Adaptation \(1\)](#)

[Adaptation \(2\)](#)

[Adaptation \(3\)](#)

Adaptation works for more general weight functions λ_n under more complicated conditions

However the choice of weights λ_n on A_n and priors $\Pi_{n,\alpha}$ “interact”

For Gaussian process priors it appears that the choice of weights λ_n is inessential (v Zanten, 2008)



Adaptation (3)

[Motivation](#)

[Generalities](#)

[Examples of settings](#)

[Examples of priors](#)

[Gaussian priors](#)

[Gaussian priors-settings](#)

[Gaussian priors-proof](#)

[Gaussian priors-examples](#)

[Adaptation](#)

Adaptation

Adaptation (1)

Adaptation (2)

Adaptation (3)

With the rescaled processes we put the hyper prior on the scale:

- Choose c from some prior on $(0, \infty)$
- Given c choose $W \sim G_{\cdot/c}$

Does it work????