

Iterative solution methods for the simulation of flow in industrial glass furnaces

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Outline

Introduction

Iterative methods

Deflation

Experiments and results

Conclusions and recommendations

Industrial glass furnace



Mathematical simulation of flows

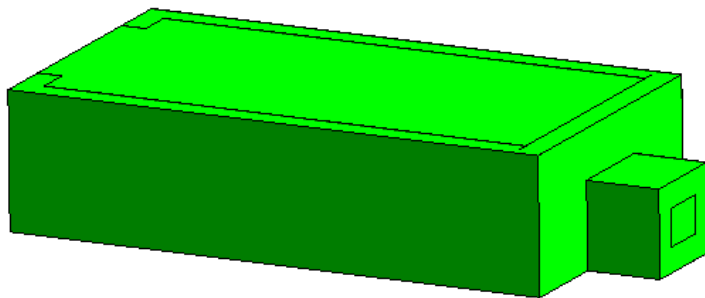
Why simulate?

- ▶ Physical experiments costly and time-consuming
- ▶ Certain physical quantities hard to measure

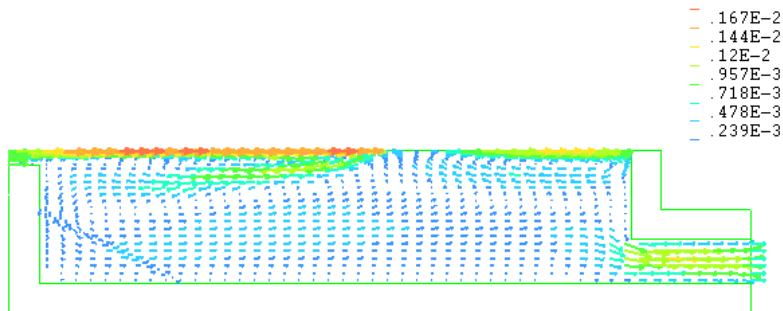
X-stream:

- ▶ CFD simulation package for glass industry
- ▶ Developed at TNO Science and Industry
- ▶ Lots of models available: combustion, turbulence, radiation, stirring, etc.

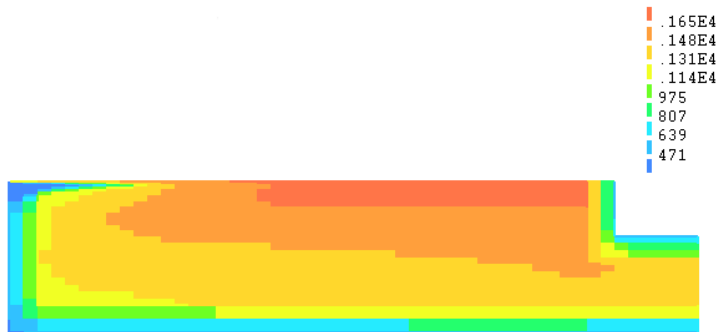
Geometry of a glass furnace



Simulation of velocities in a glass furnace

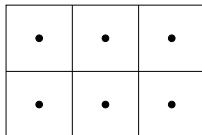


Simulation of temperature in a glass furnace

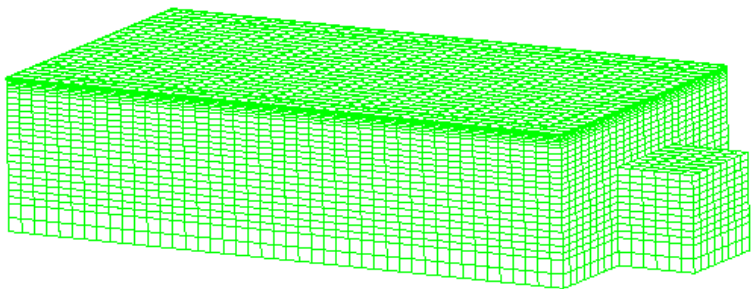


Solving mathematical flow model

- ▶ Partial differential equations arise from model
- ▶ Impossible to solve directly
- ▶ Transformation to finite number of difference equations
- ▶ Solve system of equations with iterative solution method



Grid of a glass furnace



Goal of the Master's project

Goal: improve X-stream algorithms

Focus: iterative solution methods combined with deflation

Purpose of deflation

System to be solved: $A\mathbf{x} = \mathbf{b}$

Condition number $\kappa(A) = \frac{\lambda_{\max}(A)}{\lambda_{\min}(A)}$ (A SPD)

Smaller condition number \longrightarrow faster convergence.

Deflation removes smallest eigenvalues A .

Basic idea of deflation

System to be solved: $\mathbf{Ax} = \mathbf{b}$

$$P = I - AZ(Z^T AZ)^{-1}Z^T$$

$$Q = I - Z(Z^T AZ)^{-1}Z^T A \quad (PA = AQ)$$

$$\mathbf{x} = (I - Q)\mathbf{x} + Q\mathbf{x}$$

Calculation of \mathbf{x} :

- ▶ $(I - Q)\mathbf{x} = Z(Z^T AZ)^{-1}Z^T A\mathbf{x} = Z(Z^T AZ)^{-1}Z^T \mathbf{b}$
- ▶ Solve $PA\tilde{\mathbf{x}} = P\mathbf{b}$ for $\tilde{\mathbf{x}}$
- ▶ Premultiply result with Q

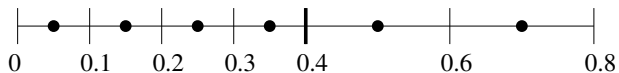
Choice of Z

Choice of Z important for convergence.

Possibilities:

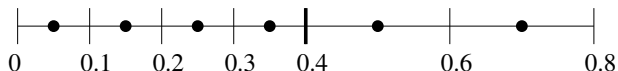
- ▶ Constant deflation (CD)
- ▶ Constant linear deflation based on grid numbering (CLD-ijk)
- ▶ Constant linear deflation based on grid coordinates (CLD-cartesian)

Constant deflation (CD)



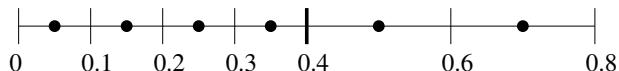
$$Z_{CD} = \begin{pmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{pmatrix}$$

Constant linear deflation based on grid numbering (CLD-ijk)



$$Z_{CLD-ijk} = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 1 & 3 & 0 & 0 \\ 1 & 4 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

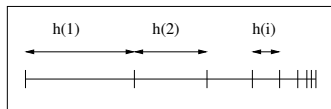
Constant linear deflation based on grid coordinates (CLD-cartesian)



$$Z_{CLD-cartesian} = \begin{pmatrix} 1 & 0.05 & 0 & 0 \\ 1 & 0.15 & 0 & 0 \\ 1 & 0.25 & 0 & 0 \\ 1 & 0.35 & 0 & 0 \\ 0 & 0 & 1 & 0.5 \\ 0 & 0 & 1 & 0.7 \end{pmatrix}$$

Experiments MATLAB

$$\frac{d^2\varphi}{dx^2} = x \sin x, \quad \varphi(0) = \varphi(\pi) = 0$$



Deflated GCR with 3 subdomains:

| n | CD | CLD-ijk | CLD-cartesian |
|-----|----|---------|---------------|
| 51 | 46 | 32 | 13 |
| 72 | 63 | 50 | 20 |

Condition number: $\kappa(A) = \frac{\lambda_{\max}(A)}{\lambda_{\min}(A)}$

$$\kappa(PA_{CLD-ijk}) = 1.4 \cdot 10^5$$

$$\kappa(PA_{CLD-cart}) = 8.9 \cdot 10^4$$

Experiments X-stream

Input:

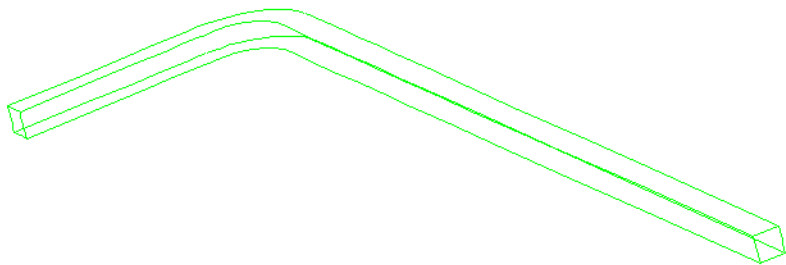
- ▶ number of inner iterations
- ▶ iterative method: SIP or GCR with CD, CLD-ijk or CLD-cartesian

Output:

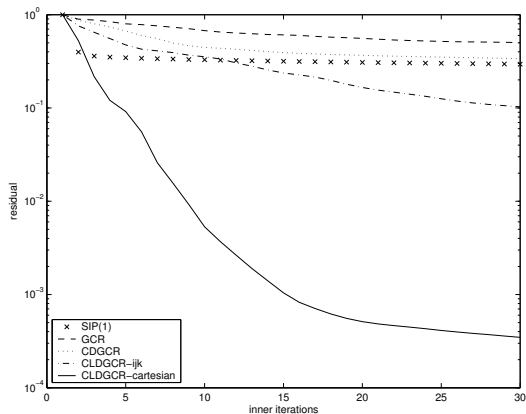
- ▶ residuals
- ▶ number of outer iterations
- ▶ wall-clock time

Note that the number of outer iterations and the wall-clock time depend on the residuals.

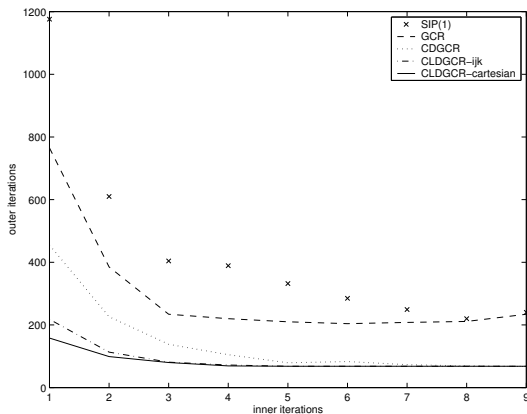
Test case channel



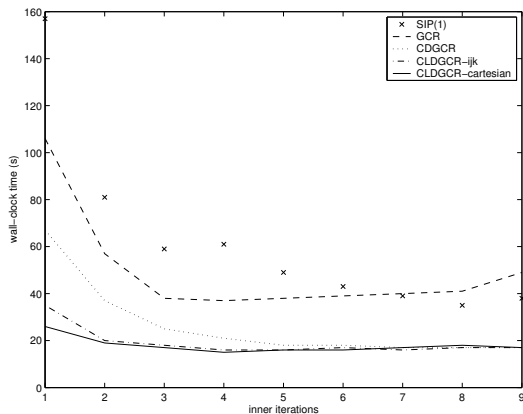
Residuals channel



Number of outer iterations channel



Wall-clock times channel



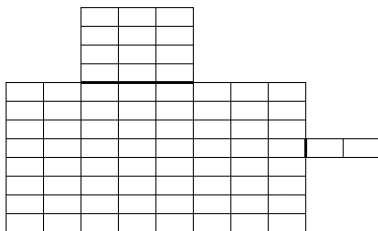
Results wall-clock times channel test case

| inner it. | $\frac{\text{SIP}(1)}{\text{GCR}}$ | $\frac{\text{SIP}(1)}{\text{CDGCR}}$ | $\frac{\text{SIP}(1)}{\text{CLDGCR-ijk}}$ | $\frac{\text{SIP}(1)}{\text{CLDGCR-cart}}$ |
|-----------|------------------------------------|--------------------------------------|-------------------------------------------|--------------------------------------------|
| 1 | 1.5 | 2.3 | 4.5 | 6.0 |
| 2 | 1.4 | 2.2 | 4.1 | 4.3 |
| 6 | 1.1 | 2.4 | 2.5 | 2.7 |
| 9 | 0.8 | 2.2 | 2.2 | 2.2 |

Using optimal number of inner iterations for each method:

| $\frac{\text{SIP}(1)}{\text{GCR}}$ | $\frac{\text{SIP}(1)}{\text{CDGCR}}$ | $\frac{\text{SIP}(1)}{\text{CLDGCR-ijk}}$ | $\frac{\text{SIP}(1)}{\text{CLDGCR-cart}}$ |
|------------------------------------|--------------------------------------|-------------------------------------------|--------------------------------------------|
| 0.9 | 2 | 2.1 | 2.3 |

Subdomain partitioning



$$E = Z^T A Z$$

600 subdomains:

E_{CD} 600×600 -matrix

E_{CLD} 2400×2400 -matrix

Conclusions

- ▶ GCR performs better with deflation
- ▶ Constant linear deflation performs better than constant deflation
- ▶ CLD-cartesian performs better than CLD-ijk
- ▶ More subdomains means less iterations
- ▶ Drawback of CLD: not suitable for large number of subdomains

Recommendations

Further research subdomain partitioning:

- ▶ How to decrease number of subdomains
- ▶ Implement a suitable sparse solver for unstructured matrices

Questions?

