



Modeling the Austenite to Ferrite Transformation by Cellular Automaton

Improving Interface Stability

Delft University of Technology

Mathias Mul

May 9, 2014

TATA STEEL

Outline

1 Introduction

Microstructure

The moving boundary problem

2 Literature

Methods

Cellular automaton

Problems

3 Model and Implementation

Model outline

Implementation

4 Results

Convergence of CA to Murray-Landis method

Improving interface stability

Grid Refinement Analysis

5 Conclusions

Next Subsection

1 Introduction

Microstructure

The moving boundary problem

2 Literature

Methods

Cellular automaton

Problems

3 Model and Implementation

Model outline

Implementation

4 Results

Convergence of CA to Murray-Landis method

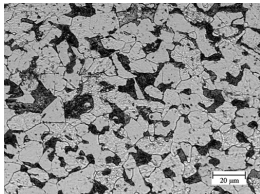
Improving interface stability

Grid Refinement Analysis

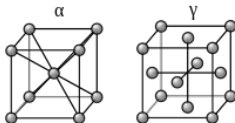
5 Conclusions

Steel microstructure

Microstructure determines mechanical properties of steel.



Ferrite/Pearlite
microstructure



Iron atom lattices

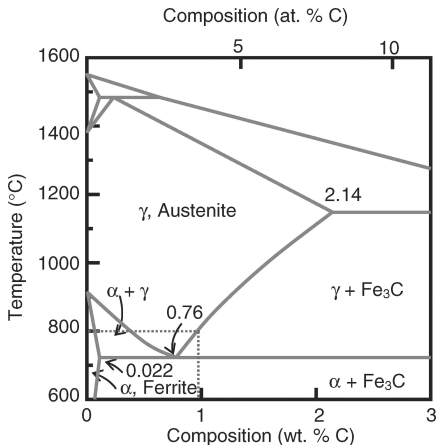
Ferrite nucleation and growth

(by Richard Huizenga,
TU Delft Materials Science and
Engineering)

Cooling down steel

High temperature: austenite

Low temperature: ferrite



Next Subsection

1 Introduction

Microstructure

The moving boundary problem

2 Literature

Methods

Cellular automaton

Problems

3 Model and Implementation

Model outline

Implementation

4 Results

Convergence of CA to Murray-Landis method

Improving interface stability

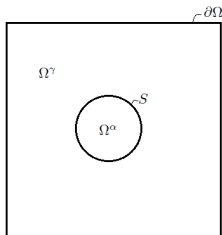
Grid Refinement Analysis

5 Conclusions

Moving boundary problem

The problem of the moving interface S can be stated as

$$\left\{ \begin{array}{ll} v_n = M\Delta G(x_s^\gamma) & \text{the normal velocity of } S \\ \frac{\partial x}{\partial t} = \nabla(D(x)\nabla x) & \text{in } \Omega^\gamma, \quad t > 0 \\ \frac{\partial x}{\partial n} = 0 & \text{on } \partial\Omega \\ \frac{\partial x}{\partial n} = -(x_s^\gamma - x^\alpha)v_n & \text{on } S \end{array} \right.$$



Next Subsection

1 Introduction

Microstructure

The moving boundary problem

2 Literature

Methods

Cellular automaton

Problems

3 Model and Implementation

Model outline

Implementation

4 Results

Convergence of CA to Murray-Landis method

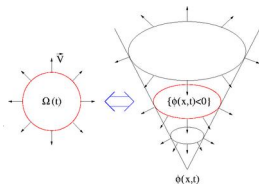
Improving interface stability

Grid Refinement Analysis

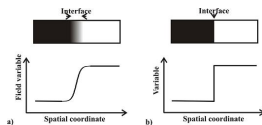
5 Conclusions

Methods for moving boundaries

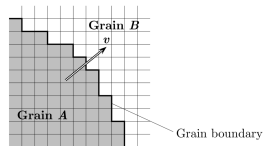
- (a) Level Set Method
- (b) Phase Field Method
- (c) Cellular Automaton



(a)



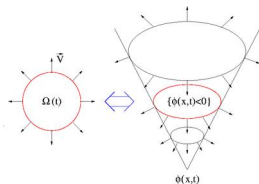
(b)



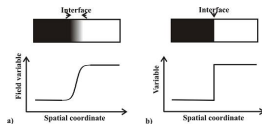
(c)

Methods for moving boundaries

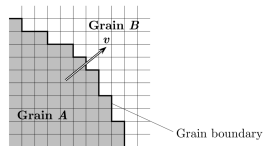
- (a) Level Set Method
- (b) Phase Field Method
- (c) Cellular Automaton



(a)



(b)



(c)

Next Subsection

1 Introduction

Microstructure

The moving boundary problem

2 Literature

Methods

Cellular automaton

Problems

3 Model and Implementation

Model outline

Implementation

4 Results

Convergence of CA to Murray-Landis method

Improving interface stability

Grid Refinement Analysis

5 Conclusions

Cellular Automaton

Model built of cells with properties

- ★ state
- ★ neighbourhood
- ★ transformation rule

example:

Next Subsection

1 Introduction

Microstructure

The moving boundary problem

2 Literature

Methods

Cellular automaton

Problems

3 Model and Implementation

Model outline

Implementation

4 Results

Convergence of CA to Murray-Landis method

Improving interface stability

Grid Refinement Analysis

5 Conclusions

1-dim CA in comparison to Murray-Landis

CA: Interface S always lies on pre-set points

ML: Interface S may freely move

Unstable interfaces

Reasons: Absence of surface tension in model, discretized spatial grid

Next Subsection

1 Introduction

Microstructure

The moving boundary problem

2 Literature

Methods

Cellular automaton

Problems

3 Model and Implementation

Model outline

Implementation

4 Results

Convergence of CA to Murray-Landis method

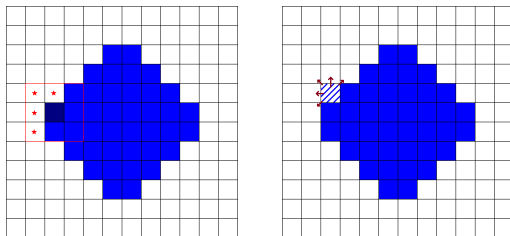
Improving interface stability

Grid Refinement Analysis

5 Conclusions

Model outline

- 1 Compute carbon concentration at interface cells
- 2 Compute growth velocity of interface cells
- 3 Compute growth length of interface cells
- 4 Transform cells according to a transformation rule
- 5 Redistribute excess carbon from newly transformed cells
- 6 Solve a time step of carbon diffusion in austenite



Next Subsection

1 Introduction

Microstructure

The moving boundary problem

2 Literature

Methods

Cellular automaton

Problems

3 Model and Implementation

Model outline

Implementation

4 Results

Convergence of CA to Murray-Landis method

Improving interface stability

Grid Refinement Analysis

5 Conclusions

Growth dynamics

For every interface cell i we define:

Growth length $\ell_i \geq 0$

Growth velocity $v_i \geq 0$

Inward growth $\lambda_i \geq 0$

The velocity v is calculated according to the classical equation

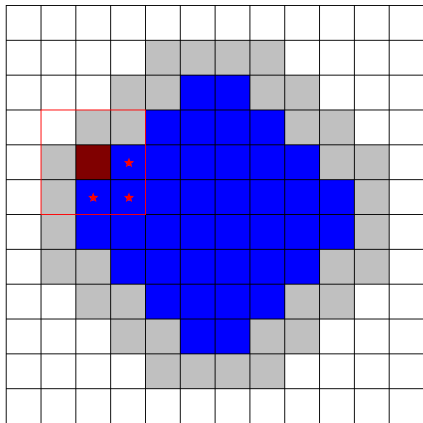
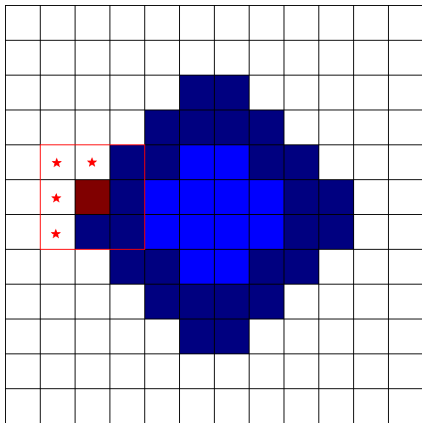
$$v = M \underbrace{\Delta G(x^{\text{interface}}, T)}_{\text{driving force}}, \quad \text{where } \Delta G : \mathbb{R}^2 \rightarrow \mathbb{R},$$

and M the interface mobility.

$$\lambda_i = \sum_{j \in \mathcal{M}_i} w_{ji} \ell_j$$

$$w_{ji} = \begin{cases} 1 & \text{cells } i \text{ and } j \text{ are direct neighbours} \\ \frac{1}{\sqrt{2}} & \text{cells } i \text{ and } j \text{ are diagonal neighbours} \end{cases},$$

Growth dynamics(2)



Forward Euler: $l_i^{k+1} = l_i^k + v_i^k$

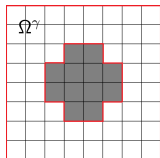
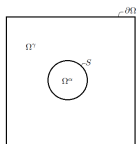
Transformation rule: $l > \Delta z$

Transformation rule: $\lambda(l) > \theta(\Delta z)$

Carbon diffusion

Find $x(t_0 + \Delta t)$ on Ω^γ such that

$$\begin{cases} \frac{\partial x}{\partial t} = \nabla(D(x)\nabla x) & \text{in } \Omega^\gamma, & t_0 \leq t \leq t_0 + \Delta t \\ \frac{\partial x}{\partial n} = 0 & \text{on } \partial\Omega^\gamma \\ x(t_0) = x_{t_0} & \text{on } \partial\Omega^\gamma \end{cases}$$



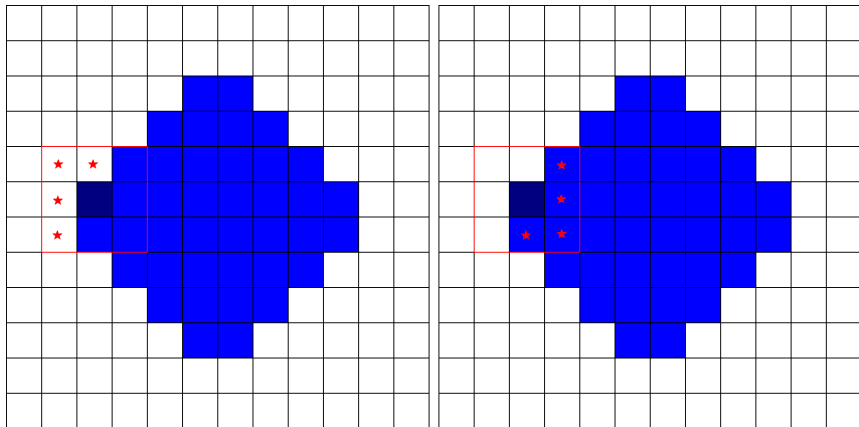
- 1 Implicit Euler
- 2 Finite Differences
- 3 Conjugate Gradient

Interface carbon smoothing

Why? As an attempt to reduce instability.

How? In two steps.

example



Next Subsection

1 Introduction

Microstructure

The moving boundary problem

2 Literature

Methods

Cellular automaton

Problems

3 Model and Implementation

Model outline

Implementation

4 Results

Convergence of CA to Murray-Landis method

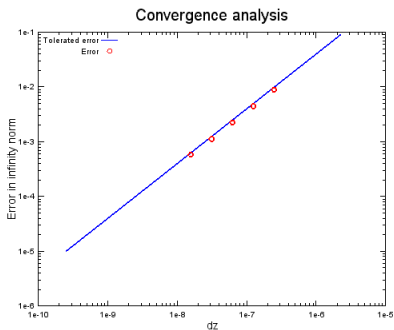
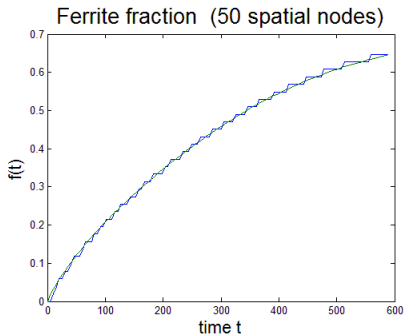
Improving interface stability

Grid Refinement Analysis

5 Conclusions

Comparison: CA to Murray-Landis

$$\Delta z \rightarrow 0, \quad \Delta t = 0.9 \frac{\Delta z}{v_{\max}}$$



Next Subsection

1 Introduction

Microstructure

The moving boundary problem

2 Literature

Methods

Cellular automaton

Problems

3 Model and Implementation

Model outline

Implementation

4 Results

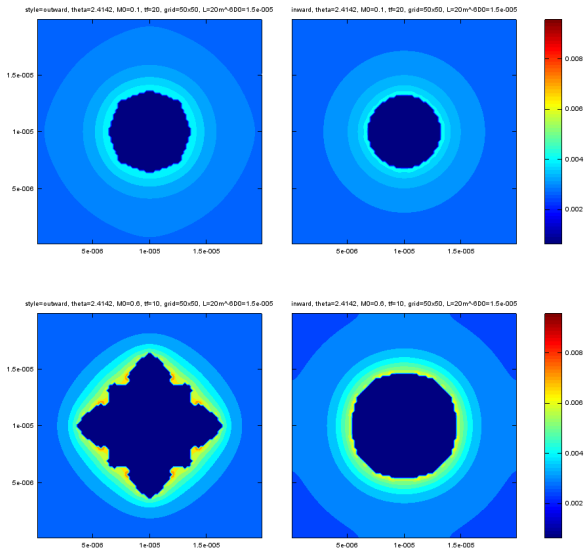
Convergence of CA to Murray-Landis method

Improving interface stability

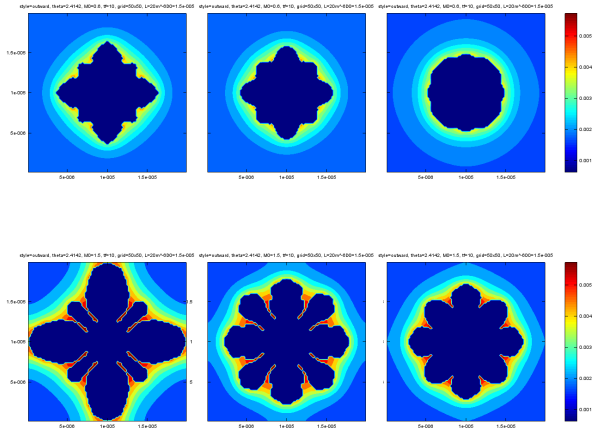
Grid Refinement Analysis

5 Conclusions

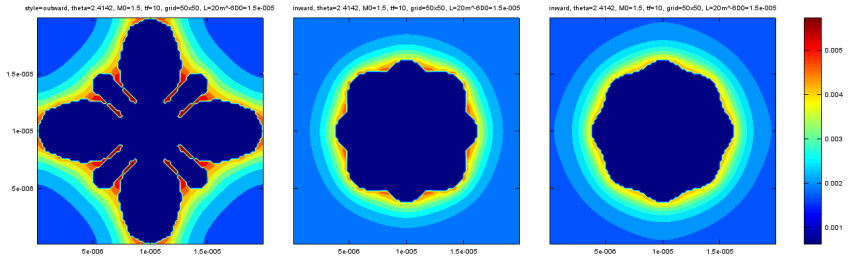
Inward growth results



Carbon smoothing results



Combined results: Inward growth & Carbon smoothing



Next Subsection

1 Introduction

Microstructure

The moving boundary problem

2 Literature

Methods

Cellular automaton

Problems

3 Model and Implementation

Model outline

Implementation

4 Results

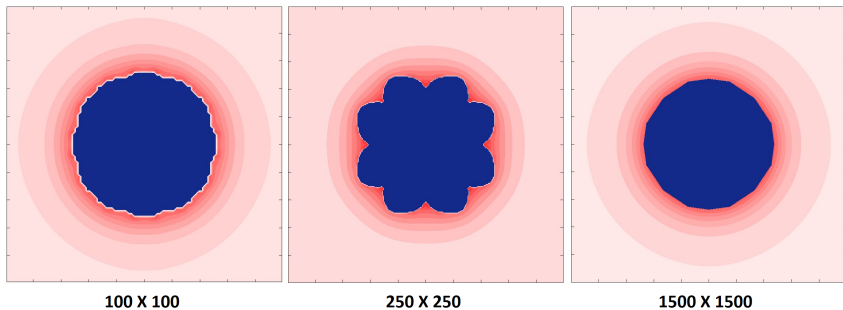
Convergence of CA to Murray-Landis method

Improving interface stability

Grid Refinement Analysis

5 Conclusions

Results on grid analysis



Conclusions and Research Questions

- ★ Inward growth seems to reduce dendritic growth and results in a circular shape
- ★ Carbon smoothing also reduces dendritic growth, smoothing area can be scaled up
- ? *Is it possible to incorporate surface tension in the model to avoid dendritic grain growth without paying for heavy computational costs?*
- ? *Are the new approaches enough for the current application?*