## On the choice of abstract projection vectors for second level preconditioners

C. Vuik ${ }^{1}$, J.M. Tang ${ }^{1}$, and R. Nabben ${ }^{2}$
${ }^{1}$ Delft University of Technology
Delft Institute of Applied Mathematics
${ }^{2}$ Technische Universität Berlin
Institut für Mathematik

## Outline

Introduction2 Second level preconditioners

3 Choice of vectors

4 Level set vectors
(5) Numerical experiments

6 Conclusions

## Bubbly flow



## Background

- Simulation of flows with bubbles and droplets
- Flow governed by the Navier-Stokes equations with unknowns $p$ an $d u$ :

$$
\left\{\begin{array}{l}
\frac{\partial u}{\partial t}+u \cdot \nabla u+\frac{1}{\rho} \nabla p=\frac{1}{\rho} \nabla \cdot \mu\left(\nabla u+\nabla u^{T}\right)+g \\
\nabla \cdot u=0
\end{array}\right.
$$

- Solution using operator-splitting methods


## Problem Setting

## Most Time-Consuming Part in Operator-Splitting Methods

Solve the linear system

$$
A x=b, \quad A \in \mathbb{R}^{n \times n}
$$

where $A$ is large, sparse, SPSD, ill-conditioned and is originating from the pressure equation

## Origin of Linear System

Poisson equation with discontinuous density $\rho$ :

$$
\operatorname{div}\left(\frac{1}{\rho} \nabla p\right)=f
$$

with Neumann boundary conditions

## Traditional Krylov Solvers

## Preconditioned Conjugate Gradients Method (PCG) ${ }^{1}$

## Solve iteratively:

$$
M^{-1} A x=M^{-1} b
$$

where $M$ is a traditional preconditioner that resembles $A$

## Requirements for Preconditioner $M$

- $M z=y$ is relatively easy to solve
- $M^{-1} A$ has a smaller condition number than $A$


## Theorem ${ }^{2}$

Exact error of PCG after iteration $j$ :

$$
\left\|x-x_{j}\right\|_{A} \leq 2\left\|x-x_{0}\right\|_{A}\left(\frac{\sqrt{\tilde{\kappa}\left(M^{-1} A\right)-1}}{\sqrt{\tilde{\kappa}\left(M^{-1} A\right)+1}}\right)^{j}
$$

[^0]
## Traditional Krylov Solvers

## Problem of PCG

The spectrum of $M^{-1} A$ contains a number of small eigenvalues

## Consequence

$\tilde{\kappa}\left(M^{-1} A\right)$ is large $\rightarrow$ Slow convergence of the iterative process

## Question

Can the convergence of PCG be improved by eliminating those small eigenvalues in some way?

## Second level preconditioners

## Second level preconditioners

## Various choices are possible

- Projection vectors

Physical vectors, eigenvectors, domain decomposition vectors (constant, linear, ...)

- Projection method

Deflation, coarse grid projection, balancing, augmented, FETI

- Implementation
sparseness, with(out) using projection properties, optimized, stability, rounding errors, ...


## Second level preconditioners

## Deflated Krylov

History

| Krylov | Ar | 1950 |
| :--- | :--- | :--- |
| Preconditioned Krylov | $M^{-1} \mathrm{Ar}$ | 1980 |
| Block Preconditioned Krylov | $\sum_{i=1}^{r}\left(M_{i}^{-1}\right) A r$ | 1990 |
| Block Preconditioned Deflated Krylov | $\sum_{i=1}^{r}\left(M_{i}^{-1}\right)$ PAr | 2000 |

## Deflated ICCG

## Preliminaries

## $A$ is SPD, Conjugate Gradients

$$
P=I-A Z E^{-1} Z^{T} \text { with } E=Z^{T} A Z
$$

and $Z=\left[z_{1} \ldots z_{r}\right]$, where $z_{1}, \ldots, z_{r}$ are independent deflation vectors.

## Properties

(1) $P^{T} Z=0$ and $P A Z=0$
(2) $P^{2}=P$
(3) $A P^{T}=P A$

## Second level preconditioners

## Deflated ICCG

## Decomposition

$$
\begin{gathered}
x=\left(I-P^{T}\right) x+P^{\top} x \\
\left(I-P^{T}\right) x=Z E^{-1} Z^{T} A x=Z E^{-1} Z^{T} b, \quad A P^{T} x=P A x=P b
\end{gathered}
$$

$$
k=0, \hat{r}_{0}=P r_{0}, p_{1}=z_{1}=L^{-T} L^{-1} \hat{r}_{0}
$$

while $\left\|\hat{r}_{k}\right\|_{2}>\varepsilon$ do

$$
k=k+1 \text {; }
$$

$$
\alpha_{k}=\frac{\left(\hat{r}_{k-1}, z_{k-1}\right)}{\left(p_{k}, P A p_{k}\right)}
$$

$$
x_{k}=x_{k-1}+\alpha_{k} p_{k}
$$

$$
\hat{r}_{k}=\hat{r}_{k-1}-\alpha_{k} P A p_{k} ;
$$

$$
z_{k}=L^{-T} L^{-1} \hat{r}_{k} ;
$$

$$
\beta_{k}=\frac{\left(\hat{r}_{k}, z_{k}\right)}{\left(\hat{r}_{k-1}, z_{k-1}\right)}
$$

$$
p_{k+1}=z_{k}+\beta_{k} p_{k}
$$

end while

## Choice of vectors

## Ideal Choice of $Z$

$Z$ consists of eigenvectors associated with small eigenvalues of $M^{-1} A$

## Problem Ideal Choice of $Z$

These eigenvectors are too expensive to compute in practice and are not sparse

## Alternative Choice of $Z$

Find projection vectors such that they

- approximate these eigenvectors
- are sparse
- are easy to parallelize

First step: Analyze small eigenvalues and corresponding eigenvectors

## Analysis of Eigenvalues and Eigenvectors

Properties of Spectrum of $M^{-1} A$
Spectrum contains two classes of small eigenvalues:

- $\mathcal{O}\left(10^{-3}\right)$-eigenvalues corresponding with bubbles
- Small $\mathcal{O}(1)$-eigenvalues

One should get rid of these eigenvalues

## Analysis of Eigenvalues and Eigenvectors

## Eigenvectors associated with $\mathcal{O}\left(10^{-3}\right)$-eigenvalues

- constant in bubbles
- linear elsewhere


## Approximations

The vectors remain good approximations of the eigenvectors if

- the linear parts are perturbed arbitrarily
- the constant part are perturbed by a constant


## Consequence

Level set projection vectors can approximate these eigenvectors
Note: the level set function is used as an indication function of the bubbles

## Level set vectors



## Projection subspace matrix

$Z=\left[\begin{array}{llll}z_{1} & z_{2} & \cdots & z_{r}\end{array}\right]$ consists of $\left(z_{j}\right)_{i}= \begin{cases}0, & x_{i} \in \Omega \backslash \bar{\Omega}_{j} \\ 1, & x_{i} \in \Omega_{j}\end{cases}$

## Subdomain Projection



## Projection subspace matrix

$Z=\left[\begin{array}{llll}z_{1} & z_{2} & \cdots & z_{r}\end{array}\right]$ consists of
$\left(z_{j}\right)_{i}= \begin{cases}0, & x_{i} \in \Omega \backslash \bar{\Omega}_{j} \\ 1, & x_{i} \in \Omega_{j}\end{cases}$

## Properties of Projection Vectors

## Level set Projection Vectors

- Projection of $\mathcal{O}\left(10^{-3}\right)$-eigenvalues to zero
- Very sparse structure
- Only a few vectors required
- Change at each time step


## Subdomain Projection Vectors

- Projection of $\mathcal{O}(1)$-eigenvalues to zero
- Sparse structure
- Reasonable number of vectors required
- The same for all time steps


## Further Analysis

## Combination of Level set and Subdomain Projection

Both approaches can be combined leading to level set-subdomain projection:


Properties of Level set-Subdomain Projection Vectors

- Projection of both $\mathcal{O}\left(10^{-3}\right)$ - and $\mathcal{O}(1)$-eigenvalues to zero
- Sparse structure
- Many level set-subdomain projection vectors are required
- Change at each time step


## Problem with 5 bubbles, contrast $10^{-6}$ and varying grid size

|  |  | $n=16^{2}$ |  | $n=32^{2}$ |  | $n=64^{2}$ |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Deflation Method | $k$ | \# It. | CPU | \# It. | CPU | \# It. | CPU |
| ICCG | - | 39 | 0.04 | 82 | 0.53 | 159 | 10.92 |
| S-DICCG $-k$ | 3 | 37 | 0.12 | 80 | 0.67 | 194 | 14.01 |
|  | 15 | 36 | 0.07 | 97 | 0.80 | 193 | 13.82 |
|  | 63 | 19 | 0.11 | 16 | 0.20 | 26 | 2.14 |
| L-DICCG- $k$ | 4 | 17 | 0.09 | 37 | 0.37 | 75 | 6.17 |
| LS-DICCG- $k$ | 11 | 14 | 0.07 | 30 | 0.29 | 54 | 4.08 |
|  | 35 | 10 | 0.08 | 21 | 0.32 | 40 | 3.05 |
|  | 83 | - | - | 15 | 0.20 | 25 | 2.05 |

## Numerical experiments

## Problem with 5 bubbles, $n=64^{2}$ and varying contrast

|  |  | $\epsilon=10^{-3}$ |  | $\epsilon=10^{-6}$ |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Deflation Method | $k$ | \# It. | CPU | \# It. | CPU |
| ICCG | - | 118 | 8.12 | 159 | 10.92 |
| S-DICCG- $k$ | 3 | 134 | 9.79 | 194 | 14.01 |
|  | 15 | 131 | 9.60 | 193 | 13.82 |
|  | 63 | 26 | 2.31 | 26 | 2.14 |
| L-DICCG- $k$ | 4 | 74 | 5.98 | 75 | 6.17 |
| LS-DICCG- $k$ | 11 | 54 | 4.05 | 54 | 4.08 |
|  | 35 | 40 | 3.08 | 40 | 3.05 |
|  | 83 | 25 | 2.46 | 25 | 2.41 |

## Problem with a varying number of bubbles, $n=64^{2}$ and contrast $10^{-6}$

| Number of bubbles | 1 |  |  | 2 |  |  | 5 |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Deflation Method | $k$ | \# It. | CPU | $k$ | \# It. | CPU | $k$ | \# It. | CPU |
| ICCG | - | 89 | 6.13 | - | 104 | 7.20 | - | 159 | 10.92 |
| S-DICCG $-k$ | 3 | 96 | 7.39 | 3 | 69 | 5.13 | 3 | 194 | 14.01 |
|  | 15 | 52 | 3.97 | 15 | 64 | 4.79 | 15 | 193 | 13.82 |
|  | 63 | 26 | 2.14 | 63 | 27 | 2.16 | 63 | 26 | 2.14 |
| L-DICCG- $k$ | 0 | - | - | 1 | 79 | 5.79 | 4 | 75 | 6.17 |
| LS-DICCG- $k$ | 7 | 67 | 5.30 | 6 | 65 | 5.11 | 11 | 54 | 4.08 |
|  | 19 | 41 | 3.14 | 24 | 42 | 3.22 | 35 | 40 | 3.05 |
|  | 67 | 26 | 2.50 | 72 | 26 | 2.11 | 83 | 25 | 2.05 |

## Conclusions

## Conclusions

- Deflation helps!
- Choice of deflation vectors is important
- Subdomain vectors give good results if the number of vectors is large enough
- Level set and Level set Subdomain vectors lead to convergence which is independent of the contrast
- Level set Subdomain vectors remove both $O\left(10^{-3}\right)$ and $O(1)$ eigenvalues


## Further information

For papers on deflation see:
http://ta.twi.tudelft.nl/nw/users/vuik/pub_it_def.html

\section*{Delft Institute of Applied Mathematics <br> | $\frac{4}{0}$ |
| :--- |
| 0 |}


[^0]:    ${ }^{1}$ M.R. Hestenes and E. Stiefel, Methods of conjugate gradients for solving linear systems, J. Research Nat. Bur. Standards, 49, pp. 409-436, 1952.
    ${ }^{2}$ D.G. Luenberger, Introduction to Linear and Nonlinear Programming, Addison-Wesley Publishing Company, 1973.

