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**TEST NUMERICAL METHODS FOR DIFFERENTIAL EQUATIONS
(CTB2400)**

Thursday June 23 2022, 13:30-16:30

Number of questions: This is an exam with 12 open questions, subdivided in 3 main questions.

Answers All answers require arguments and/or shown calculation steps. Answers without arguments or calculation steps will not give points.

Tools Only a non-graphical, non-programmable calculator is permitted. All other electronic tools are not permitted.

Assessment In total 20 points can be earned. The final not-rounded grade is given by $P/2$, where P is the number of points earned.

1. For the initial value problem $y' = f(t, y)$, $y(t_0) = y_0$, we use the following integration method:

$$\begin{cases} w_{n+1}^* = w_n + \Delta t f(t_n, w_n) \\ w_{n+1} = w_n + \frac{\Delta t}{2} (f(t_n, w_n) + f(t_{n+1}, w_{n+1}^*)) \end{cases} \quad (1)$$

Here Δt denotes the timestep and w_n represents the numerical approximation at time t_n .

- (a) Show that the local truncation error of the integration method is of the order $\mathcal{O}(\Delta t^2)$.
(You are not allowed to use the test equation here.) (3pt.)

Consider the following initial value problem

$$\begin{cases} \frac{d^2 y}{dt^2} + 4 \frac{dy}{dt} + 4y = \cos \pi t, \\ y(0) = 1, \quad \frac{dy}{dt}(0) = 0. \end{cases} \quad (2)$$

- (b) Show that the above initial value problem can be written as

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}' = \begin{pmatrix} 0 & 1 \\ -4 & -4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 0 \\ \cos \pi t \end{pmatrix}. \quad (3)$$

Give the initial conditions for $x_1(0)$ and $x_2(0)$ as well. (1pt.)

- (c) Calculate one step with integration method (1), in which $\Delta t = 0.5$ and $t_0 = 0$, applied to (3) and use the given initial conditions. (2pt.)
- (d) Show that the amplification factor for this integration method is given by: $Q(\lambda \Delta t) = 1 + \lambda \Delta t + \frac{(\lambda \Delta t)^2}{2}$. (2pt.)
- (e) Examine for which stepsizes Δt , the integration method (1), applied to the initial value problem (3), is stable. (2pt.)

2. In this exercise an estimate is determined for the velocity of a bike. The measured distances of the bike from the starting line are given in the table below.

t (s)	0	10	20
$d(t)$ (m)	0	40	100

- (a) Give the first order backward difference formula for $d'(2h)$ and use this to determine an estimate of the velocity for $t = 20$. (1 pt.)
- (b) We are looking for a difference formula of the first derivative of d in $2h$ of the form:

$$Q(h) = \frac{\alpha_0}{h}d(0) + \frac{\alpha_1}{h}d(h) + \frac{\alpha_2}{h}d(2h), \text{ such that } Q(h) - d'(2h) = O(h^2).$$

In the remainder of this exercise we use this formula. Show that the coefficients α_0 , α_1 and α_2 should satisfy the next system:

$$\begin{aligned} \frac{\alpha_0}{h} + \frac{\alpha_1}{h} + \frac{\alpha_2}{h} &= 0, \\ -2\alpha_0 - \alpha_1 &= 1, \\ 2\alpha_0 h + \frac{1}{2}\alpha_1 h &= 0. \end{aligned}$$

(2 pt.)

- (c) The solution of this system is given by $\alpha_0 = \frac{1}{2}$, $\alpha_1 = -2$ and $\alpha_2 = \frac{3}{2}$. Show that the truncation error can be written as: $Q(h) - d'(2h) = O(h^2)$. (1 pt.)
- (d) Use $\alpha_0 = \frac{1}{2}$, $\alpha_1 = -2$ and $\alpha_2 = \frac{3}{2}$ in $Q(h)$ to give an estimate of the velocity at $t = 20$. (1 pt.)

3. We derive and use **Newton-Raphson's method** to solve a nonlinear problem.

- (a) Given is the *scalar* nonlinear problem:

$$\text{Find } p \in \mathbb{R} \text{ such that } f(p) = 0. \quad (4)$$

Derive Newton-Raphson's formula (a graphical explanation is also allowed), given by

$$p_n = p_{n-1} - \frac{f(p_{n-1})}{f'(p_{n-1})}, \text{ for } n \geq 1 \quad (5)$$

(2 pt.)

- (b) Derive Newton-Raphson's method for the *general* nonlinear problem:

$$\text{Find } \mathbf{p} \in \mathbb{R}^m \text{ such that } \mathbf{f}(\mathbf{p}) = \mathbf{0}. \quad (6)$$

(1 pt.)

- (c) Perform **one** step of Newton-Raphson's method applied to the following nonlinear problem for w_1 and w_2 :

$$\begin{cases} 18w_1 - 9w_2 + w_1^2 = 0, \\ -9w_1 + 18w_2 + w_2^2 = 9. \end{cases} \quad (7)$$

Use $w_1 = w_2 = 0$ as the initial estimate. (2 pt.)

For the answers of this test we refer to:

<http://homepage.tudelft.nl/d2b4e/wi3097/tentamen.html>