

**ANSWERS OF THE TEST NUMERICAL METHODS FOR DIFFERENTIAL
 EQUATIONS
 (CTB2400)**

Thursday June 27 2024, 13:30-16:30

1. (a) Consider the test equation $y' = \lambda y$, then it follows that

$$k_1 = \lambda \Delta t w_n \quad (1)$$

$$k_2 = \lambda \Delta t \left(w_n + \frac{1}{2} \lambda \Delta t w_n \right) \quad (2)$$

$$= \left(\lambda \Delta t + \frac{1}{2} (\lambda \Delta t)^2 \right) w_n \quad (3)$$

$$k_3 = \lambda \Delta t \left(w_n - \lambda \Delta t w_n + 2 \left(\lambda \Delta t + \frac{1}{2} (\lambda \Delta t)^2 \right) w_n \right) \quad (4)$$

$$= (\lambda \Delta t + (\lambda \Delta t)^2 + (\lambda \Delta t)^3) w_n \quad (5)$$

$$w_{n+1} = w_n + \alpha \lambda \Delta t w_n + \beta \left(\lambda \Delta t + \frac{1}{2} (\lambda \Delta t)^2 \right) w_n \quad (6)$$

$$+ \gamma (\lambda \Delta t + (\lambda \Delta t)^2 + (\lambda \Delta t)^3) w_n \quad (7)$$

$$= \left(1 + (\alpha + \beta + \gamma) \lambda \Delta t + \left(\frac{1}{2} \beta + \gamma \right) (\lambda \Delta t)^2 + \gamma (\lambda \Delta t)^3 \right) w_n \quad (8)$$

Hence the amplification factor is given by

$$Q(\lambda \Delta t) = 1 + (\alpha + \beta + \gamma) \lambda \Delta t + \left(\frac{1}{2} \beta + \gamma \right) (\lambda \Delta t)^2 + \gamma (\lambda \Delta t)^3. \quad (9)$$

(b) The local truncation error for the test equation $y' = \lambda y$ is given by

$$\tau_{n+1}(\Delta t) = \frac{e^{\lambda \Delta t} - Q(\lambda \Delta t)}{\Delta t} y_n. \quad (10)$$

The Taylor Series around 0 for $e^{\lambda \Delta t}$ is:

$$e^{\lambda \Delta t} = 1 + \lambda \Delta t + \frac{1}{2} (\lambda \Delta t)^2 + \frac{1}{6} (\lambda \Delta t)^3 + \mathcal{O}(\Delta t^4). \quad (11)$$

Hence, this gives

$$e^{\lambda \Delta t} - Q(\lambda \Delta t) = (1 - \alpha - \beta - \gamma) \lambda \Delta t + \left(\frac{1}{2} - \frac{1}{2} \beta - \gamma \right) (\lambda \Delta t)^2 \quad (12)$$

$$+ \left(\frac{1}{6} - \gamma \right) (\lambda \Delta t)^3 + \mathcal{O}(\Delta t^4). \quad (13)$$

and hence $\tau_{n+1}(\Delta t) = \mathcal{O}(\Delta t^3)$ only if

$$\alpha + \beta + \gamma = 1, \quad (14)$$

$$\frac{1}{2} \beta + \gamma = \frac{1}{2}, \quad (15)$$

$$\gamma = \frac{1}{6}, \quad (16)$$

$$(17)$$

which have as solution

$$\alpha = \frac{1}{6}, \quad (18)$$

$$\beta = \frac{2}{3}, \quad (19)$$

$$\gamma = \frac{1}{6}. \quad (20)$$

$$(21)$$

(c) Let $x_1 = y$ and $x_2 = y'$, then it follows that $y'' = x_2'$, and hence we get

$$\begin{aligned} 2x_2' + 2x_2 + x_1 &= 2t, \\ x_2 &= x_1'. \end{aligned} \quad (22)$$

This expression is written as

$$\begin{aligned} x_1' &= x_2, \\ x_2' &= -\frac{1}{2}x_1 - x_2 + t. \end{aligned} \quad (23)$$

Finally, we get the following matrix-form:

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}' = \begin{bmatrix} 0 & 1 \\ -\frac{1}{2} & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ t \end{bmatrix}. \quad (24)$$

Here, we have $A = \begin{bmatrix} 0 & 1 \\ -\frac{1}{2} & -1 \end{bmatrix}$ and $f = \begin{bmatrix} 0 \\ t \end{bmatrix}$. The initial conditions are given by $\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

(d) To this extent, we determine the eigenvalues of the matrix A . Subsequently, these eigenvalues are substituted into the amplification factor. The eigenvalues of A are given by $-\frac{1}{2} \pm \frac{1}{2}i$. Using $\Delta t = 2$, it follows that

$$Q(\lambda\Delta t) = 1 + \lambda\Delta t + \frac{1}{2}\lambda^2\Delta t^2 + \frac{1}{6}\lambda^3\Delta t^3 \quad (25)$$

$$= 1 + (-1 + i) + \frac{1}{2}(-1 + i)^2 + \frac{1}{6}(-1 + i)^3 \quad (26)$$

$$= \frac{1}{3} - \frac{1}{3}i. \quad (27)$$

Herewith, it follows that $|Q(\lambda\Delta t)|^2 = \frac{2}{9} < 1$. Hence for $\Delta t = 2$, it follows that the method applied to the given system is stable. Note that this conclusion holds for both the eigenvalues of A since they are complex conjugates.

(e) The given method, applied to the system $\underline{x}' = A\underline{x} + \underline{f}$, gives

$$\left\{ \begin{aligned} \underline{k}_1 &= \Delta t (A\underline{w}_n + \underline{f}(t_n)) \\ \underline{k}_2 &= \Delta t (A(\underline{w}_n + \frac{1}{2}\underline{k}_1) + \underline{f}(t_n + \frac{1}{2}\Delta t)) \\ \underline{k}_3 &= \Delta t (A(\underline{w}_n - \underline{k}_1 + 2\underline{k}_2) + \underline{f}(t_n + \Delta t)) \\ \underline{w}_{n+1} &= \underline{w}_n + \frac{1}{6}(\underline{k}_1 + 4\underline{k}_2 + \underline{k}_3) \end{aligned} \right. \quad (28)$$

With the initial condition and $\Delta t = 2$, this gives

$$\left\{ \begin{array}{l} \underline{k}_1 = \begin{bmatrix} 2 \\ -3 \end{bmatrix} \\ \underline{k}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \\ \underline{k}_3 = \begin{bmatrix} 12 \\ -5 \end{bmatrix} \\ \underline{w}_1 = \begin{bmatrix} 8/3 \\ 1/3 \end{bmatrix} \end{array} \right. \quad (29)$$

2. (a) First, we check the boundary conditions:

$$u(0) = 0 - \frac{1 - e^0}{1 - e} = \frac{1 - 1}{1 - e} = 0, \quad u(1) = 1 - \frac{1 - e^1}{1 - e} = 0. \quad (30)$$

Further, we have

$$u'(x) = 1 + \frac{e^x}{1 - e}, \quad (31)$$

$$u''(x) = \frac{e^x}{1 - e}. \quad (32)$$

Hence, we immediately see

$$-u''(x) + u'(x) = -\frac{e^x}{1 - e} + 1 + \frac{e^x}{1 - e} = 1. \quad (33)$$

Hence, the solution $u(x) = 1 - \frac{1 - e^x}{1 - e}$ satisfies the differential and the boundary conditions, and therewith $u(x)$ is the solution to the boundary value problem (uniqueness can be demonstrated in a straightforward way, but this was not asked for).

(b) The domain of computation, being $(0, 1)$, is divided into subintervals with mesh points, we set $x_j = j\Delta x$, where we use n unknowns, such that $x_{n+1} = (n+1)\Delta x = 1$. We are looking for a discretization with an error of second order, $O((\Delta x)^2)$. To this extent, we use the following central differences approximation at x_j :

$$u'(x_j) \approx \frac{u(x_{j+1}) - u(x_{j-1}))}{2\Delta x}, \quad \text{for } j \in \{1, \dots, n\}. \quad (34)$$

We note that the above formula can be derived formally by writing the derivative as

$$u'(x_j) = \frac{\alpha_0 u(x_{j-1}) + \alpha_1 u(x_j) + \alpha_2 u(x_{j+1}))}{\Delta x}, \quad (35)$$

and solve α_0 , α_1 and α_2 from checking the zeroth, first and second order derivatives of $u(x)$. Further, the second order derivative is approximated by

$$u''(x_j) \approx \frac{u(x_{j+1}) - 2u(x_j) + u(x_{j-1}))}{(\Delta x)^2}. \quad (36)$$

Since we approximate the derivatives at the point x_j , we use Taylor series expansion about x_j , to obtain:

$$\begin{aligned} u(x_{j+1}) &= u(x_j + \Delta x) = u(x_j) + \Delta x u'(x_j) + \frac{(\Delta x)^2}{2} u''(x_j) + \frac{(\Delta x)^3}{6} u'''(x_j) + O((\Delta x)^4), \\ u(x_{j-1}) &= u(x_j - \Delta x) = u(x_j) - \Delta x u'(x_j) + \frac{(\Delta x)^2}{2} u''(x_j) - \frac{(\Delta x)^3}{6} u'''(x_j) + O((\Delta x)^4), \end{aligned} \quad (37)$$

This gives

$$\begin{aligned} & -\frac{u(x_{j+1}) - 2u(x_j) + u(x_{j-1}))}{(\Delta x)^2} + \frac{u(x_{j+1}) - u(x_{j-1}))}{2\Delta x} = -u''(x_j) + u'(x_j) \\ & + \frac{O((\Delta x)^3)}{2\Delta x} + \frac{O((\Delta x)^4)}{(\Delta x)^2} = -u''(x_j) + u'(x_j) + O((\Delta x)^2). \end{aligned} \quad (38)$$

Hence the error is second order, that is $O((\Delta x)^2)$. Next, we neglect the truncation error, and set $w_j := u(x_j)$ to get

$$-\frac{w_{j+1} - 2w_j + w_{j-1}}{(\Delta x)^2} + \frac{w_{j+1} - w_{j-1}}{2\Delta x} = 1, \text{ for } j \in \{1, \dots, n\}. \quad (39)$$

At the boundaries, we see for $j = 1$ and $j = n$, upon substituting $w_0 = 0$ and $w_{n+1} = 0$, respectively:

$$\begin{aligned} -\frac{w_2 - 2w_1 + 0}{(\Delta x)^2} + \frac{w_2 - 0}{2\Delta x} &= 1, \\ -\frac{0 - 2w_n + w_{n-1}}{(\Delta x)^2} + \frac{0 - w_{n-1}}{2\Delta x} &= 1. \end{aligned} \quad (40)$$

This can be rewritten more neatly as follows:

$$\begin{aligned} \frac{-w_2 + 2w_1}{(\Delta x)^2} + \frac{w_2}{2\Delta x} &= 1, \\ \frac{2w_n - w_{n-1}}{(\Delta x)^2} - \frac{w_{n-1}}{2\Delta x} &= 1. \end{aligned} \quad (41)$$

(c) Next, we use $\Delta x = 1/4$, then, from equations (39) and (41), one obtains the following system

$$32w_1 - 14w_2 = 1 \quad (42)$$

$$-18w_1 + 32w_2 - 14w_3 = 1 \quad (43)$$

$$-18w_2 + 32w_3 = 1 \quad (44)$$

3. (a) The equation that needs to be solved is

$$f(p_0) + \frac{f(p_1) - f(p_0)}{p_1 - p_0}(p_2 - p_0) = 0.$$

Solving this equation gives the steps:

$$\begin{aligned} & \frac{f(p_1) - f(p_0)}{p_1 - p_0}(p_2 - p_0) = -f(p_0), \\ \Rightarrow & p_2 - p_0 = -\frac{p_1 - p_0}{f(p_1) - f(p_0)}f(p_0), \\ \Rightarrow & p_2 = p_0 - \frac{p_1 - p_0}{f(p_1) - f(p_0)}f(p_0). \end{aligned}$$

We write the above as one quotient:

$$\begin{aligned} p_2 &= \frac{f(p_1) - f(p_0)}{f(p_1) - f(p_0)}p_0 - \frac{p_1 - p_0}{f(p_1) - f(p_0)}f(p_0), \\ \Rightarrow p_2 &= \frac{p_0f(p_1) - p_1f(p_0)}{f(p_1) - f(p_0)}. \end{aligned} \tag{45}$$

Now we have two options:

- A. Rewrite the above formula to the form given in the exercise, with $n = 2$, and conclude the formula for K_1 ;
- B. Fill in the formula for K_1 into the formula for p_n , with $n = 2$, given in the exercise and show this results in the same formula.

Note: Only one of the options has to be present within your answer and earns at most $1/2$ point.

Option A: We can rewrite Equation (45) to:

$$\begin{aligned} p_2 &= \frac{p_0f(p_1) - p_1f(p_0)}{f(p_1) - f(p_0)}, \\ \Rightarrow p_2 &= \frac{p_0f(p_1) - p_1f(p_0) - p_1f(p_1) + p_1f(p_1)}{f(p_1) - f(p_0)}, \\ \Rightarrow p_2 &= \frac{p_1(f(p_1) - f(p_0)) - (p_1 - p_0)f(p_1)}{f(p_1) - f(p_0)}, \\ \Rightarrow p_2 &= p_1 - \frac{p_1 - p_0}{f(p_1) - f(p_0)}f(p_1), \end{aligned}$$

which is indeed of the form given in the exercise. Therefore, K_1 indeed has the formula

$$K_1 = \frac{f(p_1) - f(p_0)}{(p_1 - p_0)}.$$

Option B: The formula of the exercise, with $n = 2$ and the given formula for K_1 is:

$$p_2 = p_1 - \frac{p_1 - p_0}{f(p_1) - f(p_0)}f(p_1).$$

We write the above as one quotient:

$$p_2 = \frac{f(p_1) - f(p_0)}{f(p_1) - f(p_0)} p_1 - \frac{p_1 - p_0}{f(p_1) - f(p_0)} f(p_1),$$

$$\Rightarrow p_2 = \frac{p_0 f(p_1) - p_1 f(p_0)}{f(p_1) - f(p_0)}.$$

The above equation is equal to Equation (45). Therefore, K_1 indeed has the formula

$$K_1 = \frac{f(p_1) - f(p_0)}{p_1 - p_0}.$$

- (b) *Note: Every miscalculation in the calculation of K_1 gives a subtraction of $1/4$ point, with at most $1/2$ point being subtracted.*

Given that $p_0 = 1$ and $p_1 = 2$, we first calculate K_1 , using the values from the given table:

$$\begin{aligned} K_1 &= \frac{f(p_1) - f(p_0)}{p_1 - p_0}, \\ &= \frac{f(2) - f(1)}{2 - 1}, \\ &= f(2) - f(1), \\ &= 2 - (-1), \\ &= 3. \end{aligned}$$

Note: Every miscalculation in the calculation of p_2 gives a subtraction of $1/4$ point, with at most $1/2$ point being subtracted.

Note: The value of p_2 should be consistent with your value for K_1 .

Now p_2 can be calculated with the Secant method, with $n = 2$ and the values from the given table:

$$\begin{aligned} p_2 &= p_1 - \frac{f(p_1)}{K_1}, \\ &= 2 - \frac{f(2)}{3}, \\ &= 2 - \frac{2}{3}, \\ &= \frac{4}{3}. \end{aligned}$$

- (c) The formula for K_2 is given by

$$K_2 = \frac{f(p_2) - f(p_1)}{p_2 - p_1}.$$

Motivation could be a repetition of the derivation of K_1 . It is also sufficient if a motivation is given that all indices are increased by 1. No motivation gives a subtraction of $1/2$ point.

Note: Every miscalculation in the calculation of K_2 gives a subtraction of $1/4$ point, with at most $3/4$ point being subtracted.

Note: The value of K_2 should be consistent with your formula for K_2 .

This formula gives

$$\begin{aligned} K_2 &= \frac{f(p_2) - f(p_1)}{p_2 - p_1}, \\ &= \frac{f(\frac{4}{3}) - f(2)}{\frac{4}{3} - 2}, \\ &= \frac{(-\frac{2}{9}) - 2}{-\frac{2}{3}}, \\ &= \frac{-\frac{20}{9}}{-\frac{2}{3}}, \\ &= \frac{10}{3}, \end{aligned}$$

Note: Every miscalculation in the calculation of p_3 gives a subtraction of $1/4$ point, with at most $3/4$ point being subtracted.

Note: The value of p_3 should be consistent with your value for K_2 .

and finally

$$\begin{aligned} p_3 &= p_2 - \frac{f(p_2)}{K_2}, \\ &= \frac{4}{3} - \frac{f(\frac{4}{3})}{\frac{10}{3}}, \\ &= \frac{4}{3} - \frac{-\frac{2}{9}}{\frac{10}{3}}, \\ &= \frac{4}{3} - \frac{1}{15}, \\ &= \frac{7}{5}. \end{aligned}$$