DELFT UNIVERSITY OF TECHNOLOGY FACULTY OF ELECTRICAL ENGINEERING, MATHEMATICS AND COMPUTER SCIENCE

Examiner responsible: C. Vuik Examination reviewer: D. den Ouden-van der Horst

## TEST NUMERICAL METHODS FOR DIFFERENTIAL EQUATIONS (CTB2400) Tuesday July 16 2024, 13:30-16:30

Number of questions: This is an exam with 12 open questions, subdivided in 3 main questions.

- **Answers** All answers require arguments and/or shown calculation steps. Answers without arguments or calculation steps will not give points.
- **Tools** Only a non-graphical, non-programmable calculator is permitted. All other electronic tools are not permitted.
- Assessment In total 20 points can be earned. The final not-rounded grade is given by P/2, where P is the number of points earned.
  - 1. A method to integrate the initial value problem defined by  $y' = f(t, y), y(t_0) = y_0$ , is given by

$$w_{n+1} = w_n + (1 - \theta)\Delta t f(t_n, w_n) + \theta \Delta t f(t_{n+1}, w_{n+1}),$$

where  $\Delta t$  denotes the time-step,  $w_n$  represents the numerical solution at time  $t_n$  and  $0 \le \theta \le 1$ .

(a) The *amplification factor* of this method is given by

$$Q(\lambda \Delta t) = \frac{1 + (1 - \theta)\lambda \Delta t}{1 - \theta \lambda \Delta t}.$$

Derive this amplification factor for the given method.

- (b) Show that the *local truncation error* of the given method is  $\mathcal{O}(\Delta t)$  in general for the test equation  $y' = \lambda y$ . Also determine for which value of  $\theta$  the method is  $\mathcal{O}(\Delta t^2)$ .  $(3\frac{1}{2} \text{ pt.})$  *Hint:*  $e^x = 1 + x + \frac{1}{2}x^2 + \mathcal{O}(x^3)$ . *Hint:*  $\frac{1}{1-x} = 1 + x + x^2 + \mathcal{O}(x^3)$  for |x| < 1.
- (c) Take  $\theta = \frac{1}{2}$ . Given is the initial value problem

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}' = \begin{bmatrix} -1 & -3 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix},$$
 (1)

with initial conditions  $x_1(0) = 1, x_2(0) = 0.$ Is the given method applied to this initial value problem *stable* for  $\Delta t = 1$ ? (3<sup>1</sup>/<sub>2</sub> pt.)

(d) Perform one step with the given method with  $\Delta t = 1$ ,  $\theta = \frac{1}{2}$  and  $t_0 = 0$  for the initial value problem (1) and the given initial conditions.  $(1\frac{1}{2} \text{ pt.})$ 



$$(1\frac{1}{2} \text{ pt.})$$

2. We want to find an approximation of  $\sqrt{3}$ . Therefore we consider the fixed-point problem

x = g(x),

on the interval [1, 2], where the function g is defined as

$$g(x) = -\frac{1}{3}x^2 + x + 1.$$
 (2)

In the next exercises you will prove that  $p = \sqrt{3}$  is indeed the unique fixed point of g in the interval [1, 2] and that for any starting value of  $p_0 \in [1, 2]$  the fixed-point iteration

$$p_{n+1} = g(p_n),\tag{3}$$

converges to  $p = \sqrt{3}$ , and you will perform this fixed-point iteration.

- (a) Show that  $p = \sqrt{3}$  is a fixed point of the function g. (1 pt.)
- (b) Argue why g is continuous on [1, 2].
  - (c) Show that  $1 \le g(x) \le 2$  for all  $x \in [1, 2]$ . (1 pt.)
- (d) Find the smallest value k such that  $|g'(x)| \le k < 1$  for all  $x \in [1, 2]$ . (1 pt.)
- (e) Approximate  $p = \sqrt{3}$  by calculating  $p_1$  and  $p_2$  with 4 significant digits, given that  $p_0 = 2.000.$  (1 pt.)
- 3. We analyse **Lagrangian interpolation**. For given points  $x_0, x_1, \ldots, x_n$ , with their respective function values  $f(x_0), f(x_1), \ldots, f(x_n)$ , the interpolatory polynomial  $L_n(x)$  is given by

$$L_n(x) = \sum_{k=0}^n f(x_k) L_{kn}(x), \text{ with}$$
(4)

$$L_{kn}(x) = \frac{(x - x_0) \cdots (x - x_{k-1})(x - x_{k+1}) \cdots (x - x_n)}{(x_k - x_0) \cdots (x_k - x_{k-1})(x_k - x_{k+1}) \cdots (x_k - x_n)}.$$

- (a) Give the linear Lagrangian interpolatory polynomial  $L_1(x)$  with nodes  $x_0$  and  $x_1$ . (1 pt.)
- (b) Give the quadratic Lagrangian interpolatory polynomial  $L_2(x)$  with nodes  $x_0, x_1$  and  $x_2$ . (2 pt.)
- (c) Calculate  $L_n(2)$  and  $L_n(3)$  both by using linear and quadratic Lagrangian interpolation using the following measured values:

k	$x_k$	$f(x_k)$
0	1	3
1	3	6
2	4	5

(1 pt.)