DELFT UNIVERSITY OF TECHNOLOGY



FACULTY OF ELECTRICAL ENGINEERING, MATHEMATICS AND COMPUTER SCIENCE

Examiner responsible: C. Vuik

Examination reviewer: D. den Ouden-van der Horst

TEST NUMERICAL METHODS FOR DIFFERENTIAL EQUATIONS (CTB2400)

Tuesday July 15 2025, 13:30-16:30

Number of questions: This is an exam with 12 open questions, subdivided in 3 main questions.

Answers All answers require arguments and/or shown calculation steps. Answers without arguments or calculation steps will not give points.

Tools Only a non-graphical, non-programmable calculator is permitted. All other electronic tools are not permitted.

Assessment In total 20 points can be earned. The final not-rounded grade is given by P/2, where P is the number of points earned.

1. For the initial value problem y' = f(t, y), $y(t_0) = y_0$, we use the following integration method:

$$\begin{cases} w_{n+1}^* = w_n + \Delta t f(t_n, w_n) \\ w_{n+1} = w_n + \frac{\Delta t}{2} \left(f(t_n, w_n) + f(t_{n+1}, w_{n+1}^*) \right). \end{cases}$$
 (1)

Here Δt denotes the timestep and w_n represents the numerical approximation at time t_n .

(a) Show that the local truncation error of the integration method is of the order $\mathcal{O}(\Delta t^2)$. (You are not allowed to use the test equation here.) (3pt.)

Consider the following initial value problem

$$\begin{cases} \frac{d^2y}{dt^2} + 2\frac{dy}{dt} + \frac{4}{3}y = \cos t, \\ y(0) = 1, \quad \frac{dy}{dt}(0) = 0. \end{cases}$$
 (2)

(b) Show that the above initial value problem can be written as

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}' = \begin{pmatrix} 0 & 1 \\ -\frac{4}{3} & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 0 \\ \cos t \end{pmatrix}.$$
 (3)

Give the initial conditions for $x_1(0)$ and $x_2(0)$ as well.

- (c) Calculate one step with integration method (1), in which $\Delta t = 0.1$ and $t_0 = 0$, applied to (3) and use the given initial conditions. (2pt.)
- (d) Derive the amplification factor for the integration method. (2pt.)
- (e) Examine for which stepsizes Δt , the integration method (1), applied to the initial value problem (3), is stable. (2pt.)

(1pt.)

2. We have approximated a function f satisfying f(-1) = 0, f(0) = 2 and f(1) = 1 with a natural cubic spline s given by

$$s(x) = \begin{cases} -\frac{3}{4}x^3 - \frac{9}{4}x^2 + \frac{1}{2}x + 2 & \text{if } x \in [-1, 0), \\ \frac{3}{4}x^3 - \frac{9}{4}x^2 + \frac{1}{2}x + 2 & \text{if } x \in [0, 1]. \end{cases}$$
(4)

In the next exercises you will prove that s is indeed the natural cubic spline based on f. Then you will use s to approximate $f\left(-\frac{1}{2}\right)$.

- (a) Show that s, s' and s'' are continuous on the interval [-1, 1]. (2 pt.)
- (b) Show that s''(x) equals zero in the end points. (1 pt.)
- (c) Show that s(x) equals f(x) in the nodes. (1 pt.)
- (d) Approximate $f\left(-\frac{1}{2}\right)$ with the use of (4). (1 pt.)
- 3. We derive and use Newton–Raphson's Method to solve a nonlinear problem.
 - (a) Given the scalar nonlinear problem:

Find
$$p \in \mathbb{R}$$
 such that $f(p) = 0$. (5)

Derive Newton-Raphson's formula, given by

$$p_{n+1} = p_n - \frac{f(p_n)}{f'(p_n)},\tag{6}$$

to solve the problem. Explain the method with a graph. (2pt.)

- (b) Given the nonlinear problem: Find $\mathbf{p} \in \mathbb{R}^m$ such that $\mathbf{f}(\mathbf{p}) = \mathbf{0}$, where $\mathbf{f}(\mathbf{x}) \in \mathbb{R}^m$. Give the Newton–Raphson's formula for this problem. (1pt.)
- (c) Perform one step of the Newton–Raphson scheme applied to the following system for p_1 and p_2 :

$$\begin{cases}
2p_1 - p_2 + p_1 p_2 = 0, \\
-p_1 + 2p_2 + p_2^3 = 1.
\end{cases}$$
(7)

Use $p_1 = p_2 = 0$ as the initial estimate. (2pt.)