

Scientific Computing

Lecture 7

Delft University of Technology

Vandana Dwarka and Kees Vuik

October 17, 2024

Today

- Chapter 5:
 - Jacobi method
 - Gauss-Seidel (GS) method
 - Convergence
 - Block Jacobi/GS method
 - damped Jacobi/SOR

Recap: Basic Iterative Methods

Notation: u^k is the k -th iteration.

- Error: $e^k = u - u^k$
- Residual: $r^k = f - Au^k$
- Residual equation: $Ae^k = Au - Au^k = f - Au^k = r^k$

Splitting method: $A = M - N$.

$$Au = f \Rightarrow Mu^{k+1} = f + Nu^k$$

$$u^{k+1} = M^{-1}f + M^{-1}Nu^k$$

Substituting $N = M - A$ we get:

$$\begin{aligned}u^{k+1} &= M^{-1}f + M^{-1}(M - A)u^k \\ &= u^k + M^{-1}(f - Au^k) \\ &= u^k + M^{-1}(r^k)\end{aligned}$$

Recap: Convergence

Does this iterative scheme converge? I.e. $u^{k+1} \rightarrow u$ as k goes to infinity?

$$u^{k+1} = u^k + M^{-1} (f - Au^k)$$

$$u - u^{k+1} = u - u^k - M^{-1} (Au - Au^k)$$

$$e^{k+1} = e^k - M^{-1} A e^k \Rightarrow e^{k+1} = (I - M^{-1} A) e^k$$

We define the **iteration matrix** $B = I - M^{-1}A$ such that:

$$e^{k+1} = B^k e^0$$

For convergence: $\lim_{k \rightarrow \infty} \|B^k\|_2 = 0$, which using theorem 2.7.2 is equivalent to:

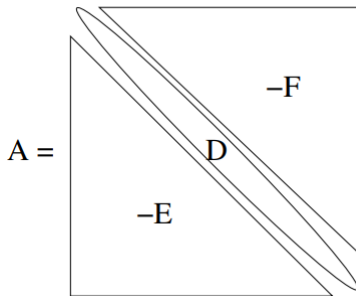
$$\lim_{k \rightarrow \infty} \|B^k\|_2 = 0 \Leftrightarrow \rho(B) < 1$$

§ 5.3: Prototypes

Different notation:

$$A = D - E - F \in \mathbb{R}^{n \times n}$$

where D , $-E$ and $-F$ denote the diagonal, the strictly lower and the strictly upper triangular part of A .

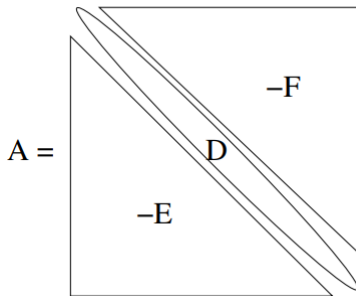


§ 5.3: Prototypes

Different notation:

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where D , $-E$ and $-F$ denote the diagonal, the strictly lower and the strictly upper triangular part of A .



Using this, we can write:

$$\hat{E} = D^{-1}E \text{ and } \hat{F} = D^{-1}F.$$

§ 5.3.1: Jacobi

Example with 1D Poisson (BC eliminated)

$A \in \mathbb{R}^{3 \times 3}$ with

$$A = \frac{1}{h^2} \begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix}, \quad f = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \quad u = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix}$$

such that $Au = f$

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such that $Au = f$

This is equivalent to:

$$\begin{aligned} 2u_1 - u_2 &= 1 \\ -u_1 + 2u_2 - u_3 &= 1 \\ -u_2 + 2u_3 &= 1 \end{aligned}$$

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But also to:

$$\begin{aligned} 2u_1 &= 1 + u_2 \\ 2u_2 &= 1 + u_1 + u_3 \\ 2u_3 &= 1 + u_2 \end{aligned}$$

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In an iterative scheme we can update using previous information!

§ 5.3.1: Jacobi

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$$2u_1 = 1 + u_2$$

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Using iteration k :

$$2u_1^{k+1} = 1 + u_2^k$$

$$2u_2^{k+1} = 1 + u_1^k + u_3^k$$

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Splitting notation:

$Mu^{k+1} = f + Nu^k$, with

$$M = \frac{1}{h^2} \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}, \quad N = \frac{1}{h^2} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

§ 5.3.1: Jacobi

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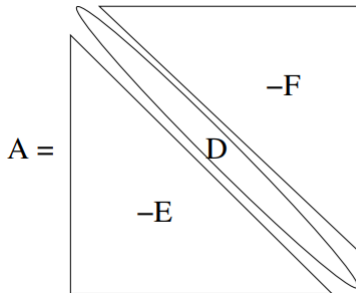
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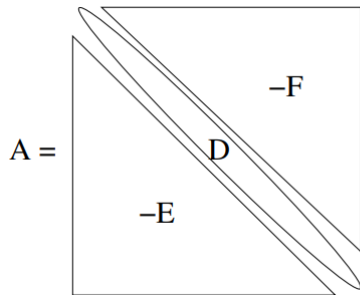
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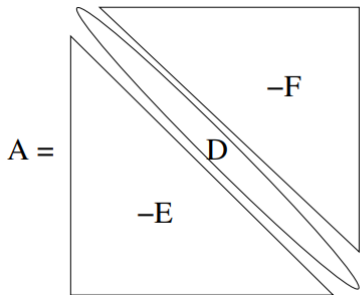


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Or equivalently: $M = D$ and $N = E + F$, in $Mu^{k+1} = f + Nu^k$

$$M = \frac{1}{h^2} \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}, N = \frac{1}{h^2} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

§ 5.3.1: Gauss-Seidel

Example with 1D Poisson (BC eliminated)

$A \in \mathbb{R}^{3 \times 3}$ with

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Jacobi:

$$2\mathbf{u}_1^{k+1} = 1 + u_2^k$$

$$2u_2^{k+1} = 1 + \mathbf{u}_1^k + u_3^k$$

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Gauss-Seidel:

$$2u_1^{k+1} = 1 + u_2^k$$

$$-\mathbf{u}_1^{k+1} + 2u_2^{k+1} = 1 + u_3^k$$

$$-\mathbf{u}_2^{k+1} + 2u_3^{k+1} = 1$$

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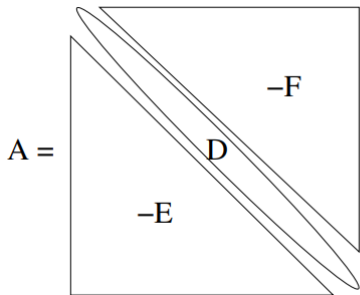
$$-\mathbf{u}_2^{k+1} + 2u_3^{k+1} = 1$$

§ 5.3.1: Gauss-Seidel

$$A = \begin{array}{|c|} \hline \begin{array}{c} \text{-F} \\ \text{D} \\ \text{-E} \end{array} \\ \hline \end{array}$$

$$= \frac{1}{h^2} \begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix}$$

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§ 5.3.1: Jacobi and GS

Jacobi:

$$u^{k+1} = D^{-1} [(E + F)u^k + f]$$

Component wise update:

$$u_i^{k+1} = \left[f_i - \sum_{j=1, j \neq i}^n a_{ij} u_j^k \right] / a_{ii}$$

GS:

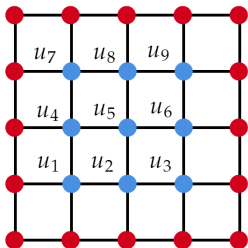
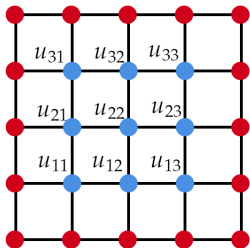
$$u^{k+1} = \hat{E}u^{k+1} + \hat{F}u^k + D^{-1}f$$

Component wise update:

$$u_i^{k+1} = \left[f_i - \sum_{j=1}^{i-1} a_{ij} u_j^{k+1} - \sum_{j=i+1}^n a_{ij} u_j^k \right] / a_{ii}$$

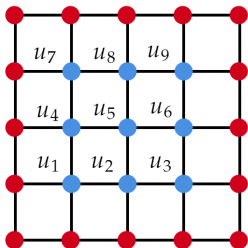
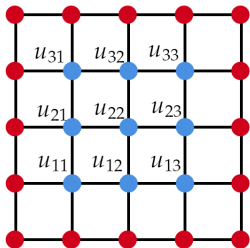
§ 5.3.1: Faster Convergence (Block methods)

Recall: x-line lexicographic ordering (2D)



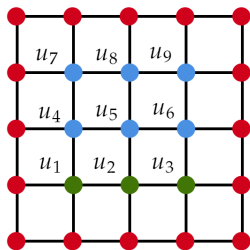
§ 5.3.1: Faster Convergence (Block methods)

Recall: x-line lexicographic ordering (2D)



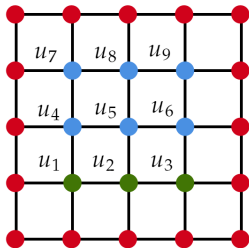
Update in blocks or 'aggregates' of u to accelerate convergence!

§ 5.3.1: Faster Convergence (Block methods)

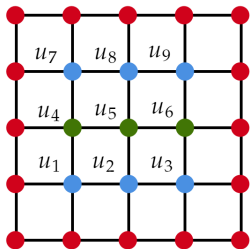


$$\hat{U}_1 = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix}$$

§ 5.3.1: Faster Convergence (Block methods)

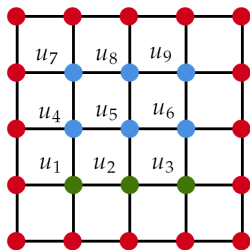


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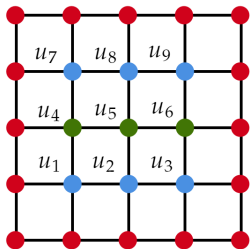


$$\hat{U}_2 = \begin{pmatrix} u_4 \\ u_5 \\ u_6 \end{pmatrix}$$

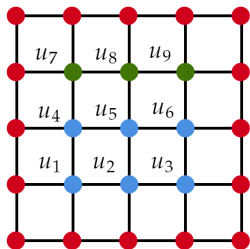
§ 5.3.1: Faster Convergence (Block methods)



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$$\hat{U}_3 = \begin{pmatrix} u_7 \\ u_8 \\ u_9 \end{pmatrix}$$

§ 5.3.1: Faster Convergence (Block methods)

Then $Au = f$ can be written as:

$$\begin{pmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{pmatrix} \begin{pmatrix} \hat{U}_1 \\ \hat{U}_2 \\ \hat{U}_3 \end{pmatrix} = \begin{pmatrix} \hat{F}_1 \\ \hat{F}_2 \\ \hat{F}_3 \end{pmatrix}.$$

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For the 2D poisson problem with elim. (lecture 3, slide 7), we get:

$$A_{11} = A_{22} = A_{33} = \frac{1}{h^2} \begin{pmatrix} 4 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 4 \end{pmatrix}$$

$$A_{12} = A_{21} = A_{23} = A_{32} = \frac{1}{h^2} \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix},$$

$$A_{13} = A_{31} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

§ 5.3.1: Faster Convergence (Block-Jacobi)

Block-Jacobi: $M = [A_{11}, A_{22}, A_{33}]$ (block-diagonal of A).

At iteration k :

$$A_{11} \hat{U}_1^{k+1} = \hat{F}_1 - A_{12} \hat{U}_2^k$$

$$A_{22} \hat{U}_2^{k+1} = \hat{F}_2 - A_{21} \hat{U}_1^k - A_{23} \hat{U}_3^k$$

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Block wise update:

$$\hat{U}_i^{k+1} = A_{i,i}^{-1} \left[F_i - \sum_{j=1, j \neq i}^q A_{i,j} \hat{U}_j^k \right] \quad \forall i = 1, \dots, q$$

§ 5.3.1: Error Propagation

For the iteration matrices $B_{JAC} = I - M_{JAC}^{-1}A$ and $B_{GS} = I - M_{GS}^{-1}A$, we get¹

$$\begin{aligned}B_{JAC} &= I - D^{-1}(D - E - F) \\ &= I - I + D^{-1}E + D^{-1}F \\ &= \hat{E} + \hat{F},\end{aligned}$$

$$\begin{aligned}B_{GS} &= I - (D - E)^{-1}(D - E - F) \\ &= I - I + (D - E)^{-1}F \\ &= (D - E)^{-1}DD^{-1}F \\ &= (I - E)^{-1}\hat{F}\end{aligned}$$

¹Note: $A = D - E - F$

§ 5.4.1: Convergence (General)

Theorem 5.4.1

$$\rho(B) = \rho(I - M^{-1}A) < 1 \Leftrightarrow \left\{ \mathbf{u}^k \right\}_{k=1}^{\infty} \text{ converges.}$$

§ 5.4.1: Convergence (General)

Theorem 5.4.1

$$\rho(B) = \rho(I - M^{-1}A) < 1 \Leftrightarrow \left\{ \mathbf{u}^k \right\}_{k=1}^{\infty} \text{ converges.}$$

Recall: **iteration matrix** $B = I - M^{-1}A$ defines error propagation:

$$e^{k+1} = B^k e^0$$

For convergence: $\lim_{k \rightarrow \infty} \|B^k\|_2 = 0$, which using theorem 2.7.2 is equivalent to:

$$\lim_{k \rightarrow \infty} \|B^k\|_2 = 0 \Leftrightarrow \rho(B) < 1$$

§ 5.4.4: Convergence (Jacobi)

Diagonal Dominance

Theorem 5.4.2

Theorem 5.4.2 Assume $A \in \mathbb{R}^{n \times n}$ to be strongly row diagonally dominant. Then the Jacobi and GaussSeidel method applied to A converge, i.e.,

$$\sum_{j=1, j \neq i}^n |a_{ij}| < |a_{ii}| \quad \forall i = 1, \dots, n \Rightarrow \|B_{GS}\|_{\infty} \leq \|B_{JAC}\|_{\infty} < 1$$

§ 5.4.4: Convergence (Jacobi)

Diagonal Dominance

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$$\sum_{j=1, j \neq i}^n |a_{ij}| < |a_{ii}| \quad \forall i = 1, \dots, n \Rightarrow \|B_{GS}\|_{\infty} \leq \|B_{JAC}\|_{\infty} < 1$$

$$\|B_{JAC}\|_{\infty} = \|\hat{E} + \hat{F}\|_{\infty} = \max_{1 \leq i \leq n} \sum_{j=1, j \neq i}^n \frac{|a_{ij}|}{|a_{ii}|} < 1 \text{ [row sum criterion]}$$

§ 5.4.4: Convergence (GS)

Lemma 5.3.1 (Elementwise bound on the Gauss-Seidel)

Assume $A \in \mathbb{R}^{n \times n}$ and assume B_{GS} to be the Gauss-Seidel iteration matrix defined by (5.19). Then

$$|B_{GS}| \leq (I - |\hat{E}|)^{-1} |\hat{F}|$$

§ 5.3.2: Richardson and damped Jacobi

- Richardson: $M_{RICH} = I$ or $M = \tau I$
- Damped Jacobi: $M_{JAC(\omega)} = \frac{1}{\omega} D$

One can show equivalence of the methods with $\tau = \omega^{-1}$ applied to $D^{-1}Au = D^{-1}f$

§ 5.3.3: Successive overrelaxation (SOR)

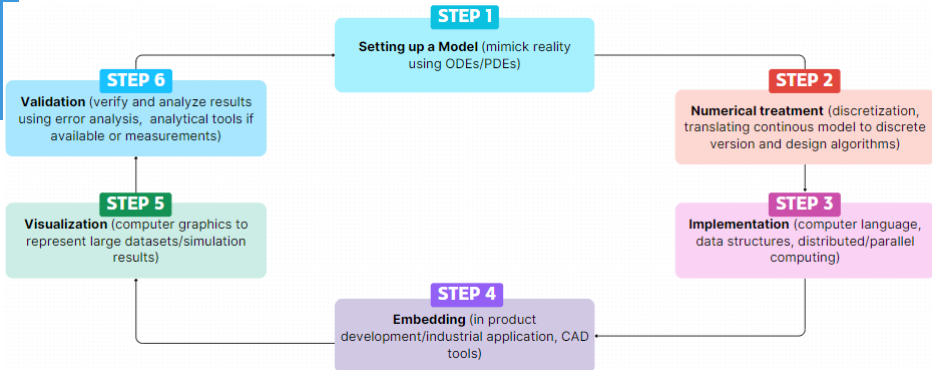
- SOR: $M_{SOR} = \frac{1}{\omega}D - E$

§ 5.3.3: Successive overrelaxation (SOR)

- SOR: $M_{SOR} = \frac{1}{\omega}D - E$

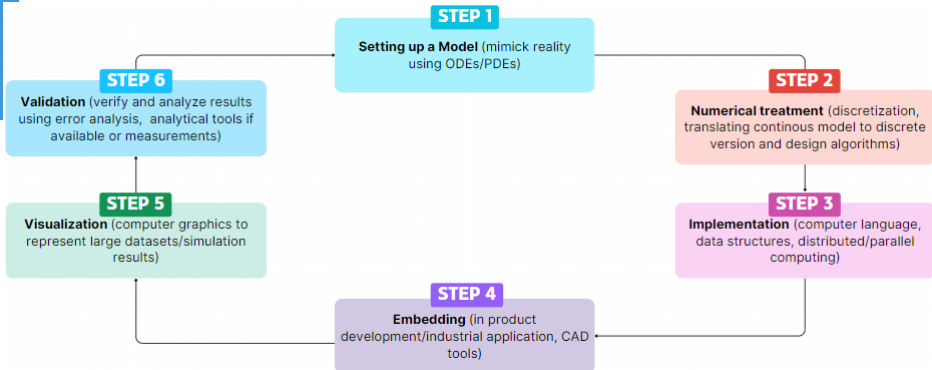
Note that this is GS with damping!

Summary (Part I of this course)



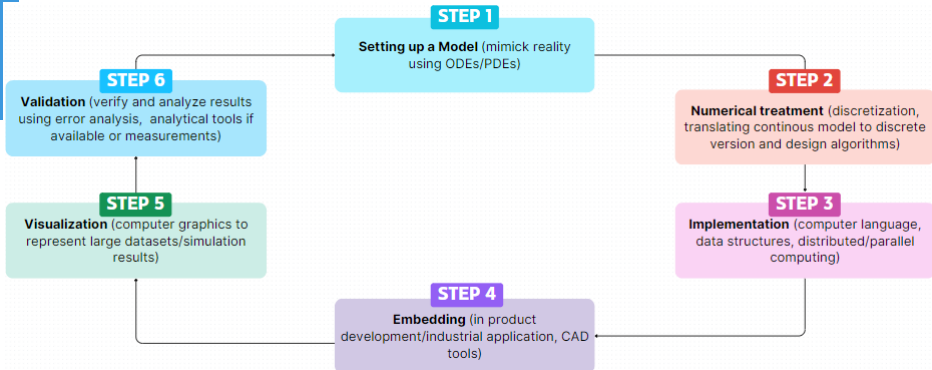
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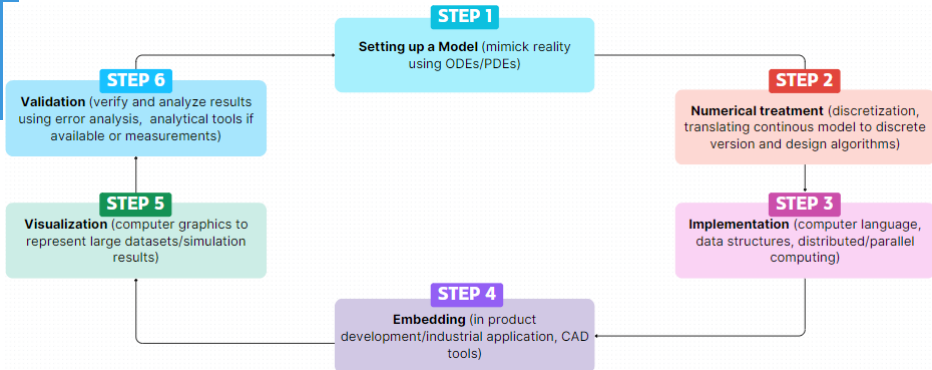
- Lecture 1-3 (step 1,2): elliptic problems, from PDE to $Au = f$ (discretization) and properties of the continuous/discrete problem
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Summary (Part I of this course)



- Lecture 1-3 (step 1,2): elliptic problems, from PDE to $Au = f$ (discretization) and properties of the continuous/discrete problem
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Summary (Part I of this course)



- Lecture 1-3 (step 1,2): elliptic problems, from PDE to $Au = f$ (discretization) and properties of the continuous/discrete problem
- Lecture 4 (step 6): metrics to perform validation steps (rounding errors, floating points, conditioning)
- Lecture 5-7 (step 2): design of algorithms to solve $Au = f$
 - Direct solvers (LU decomposition)
 - Basic iterative solvers (Jacobi, GS, Richardson)

Part II of this course

- Multigrid
- Krylov methods
- Power methods

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MSc. projects in our group [▶ \(graduation\)](#)

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- Machine learning, computational finance, discretization methods and iterative solvers.

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MSc. projects in our group [▶ \(graduation\)](#)

- Machine learning, computational finance, discretization methods and iterative solvers.
- **Projects with me:** computational and sustainable finance, plasma fusion simulation, electromagnetics simulation