

Extending the Method of Fundamental Solutions to Non Homogeneous Elastic Wave Propagation Problems

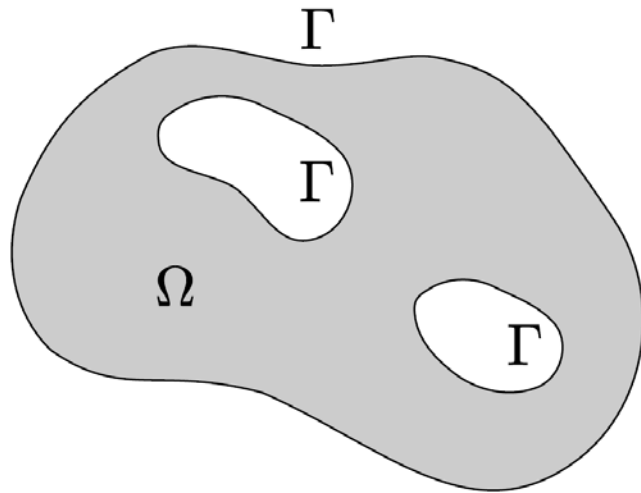
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Outline:

- Elastic Wave Propagation Problems
- The Classical Method of Fundamental Solutions (MFS)
 - Motivation and numerical formulation.
 - Theoretical and numerical results
- Extending the MFS to Non Homogeneous BVPs
- Numerical Examples
 - PDE with constant frequency
 - Interior wave scattering problem
 - A more general PDE (variable coefficients)

Elastic Wave Propagation Problems



$$\begin{cases} \mathcal{E}\mathbf{u} = 0 & \text{in } \Omega \\ \mathbf{u} = \mathbf{g} & \text{on } \Gamma \end{cases}$$

- Continuous, isotropic elastic medium $\Omega \subset \mathbb{R}^d$

- Cauchy-Navier equations of elastodynamics:

$$\mu u_{i,jj} + (\lambda + \mu) u_{j,ji} = \rho \ddot{u}_i, \quad i = 1, \dots, d.$$

- Search for a time-harmonic solution:

$$\mathbf{u}(x, t) = \mathbf{u}(x) e^{-i\omega t}$$

$$\mathcal{E}\mathbf{u} := \mu \Delta \mathbf{u} + (\lambda + \mu) \nabla(\nabla \cdot \mathbf{u}) + \rho \omega^2 \mathbf{u} = 0$$

ρ - density, λ, μ - Lamé constants, ω - frequency

Compressional wave number $k_p = \omega \sqrt{\frac{\rho}{\lambda + 2\mu}}$ and shear wave number $k_s = \omega \sqrt{\frac{\rho}{\mu}}$

Kupradze tensor (FS)

$$\mathbb{G}_\omega(x) = \frac{1}{\rho \omega^2} [k_s^2 \Phi_{k_s}(x) \mathbb{I} + \mathbb{D}(\Phi_{k_s} - \Phi_{k_p})(x)]$$

$$\mathbb{I} = \delta_{ij}$$

$$\mathbb{D} = \partial_{ij}$$

where Φ_{k_p} and Φ_{k_s} are FS for the Helmholtz operators with frequencies k_p and k_s

• Motivation for the Method of Fundamental Solutions (MFS)

- Consider the single layer potential (s.l.p.) for the solution of the Dirichlet BVP

$$\mathbf{u}(x) = (\mathcal{L}\varphi)(x) = \int_{\Gamma} \mathbb{G}_{\omega}(x - y)\varphi(y) ds_y, \quad x \in \Omega \quad (\text{continuous across } \Gamma)$$

- Define a Fredholm BIE of the first kind for the density φ

$$\int_{\Gamma} \mathbb{G}_{\omega}(x - y)\varphi(y) ds_y = \mathbf{g}(x), \quad x \in \Gamma \quad (\text{an ill-posed problem})$$

(the kernel is singular)

- Consider the s.l.p of \mathbf{u} on an auxiliary boundary $\hat{\Gamma} = \partial\hat{\Omega}$ with $\hat{\Omega} \supset \bar{\Omega}$

$$\mathbf{u}(x) = (\hat{\mathcal{L}}\varphi)(x) = \int_{\hat{\Gamma}} \mathbb{G}_{\omega}(x - y)\varphi(y) ds_y, \quad x \in \bar{\Omega} \quad (\text{regular integral})$$

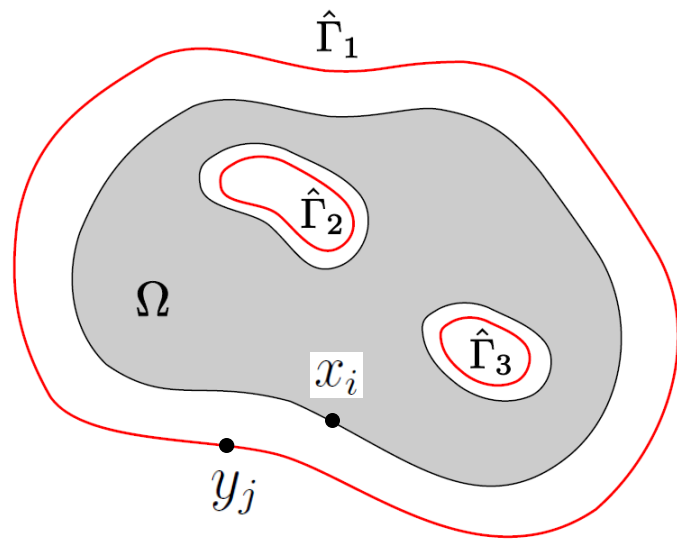
- Approximate the integral by a quadrature rule with weights γ_j and knots $y_j \in \hat{\Gamma}$

$$\mathbf{u}(x) \approx \tilde{\mathbf{u}}(x) = \sum_j \gamma_j \mathbb{G}_{\omega}(x - y_j)\varphi(y_j) \quad (\tilde{\mathbf{u}} \text{ satisfies the PDE})$$

- The approximate solution of the BIE $\hat{\mathcal{L}}\varphi = \mathbf{g}$ is reduced to the problem:

Find coefficients $\varphi(y_j) \in \mathbb{C}^d$, such that $\tilde{\mathbf{u}}$ satisfies (approximately) the BC

• The Classical Method of Fundamental Solutions



$\mathcal{Y} = \{y_j \in \hat{\Gamma} : j = 1, \dots, n\}$ source points

$$\tilde{\mathbf{u}}(x) = \sum_{j=1}^n \mathbb{G}_\omega(x - y_j) \cdot \mathbf{a}_j \quad \mathbf{a}_j \in \mathbb{C}^d, x \in \bar{\Omega}$$

$\mathcal{X} = \{x_i \in \Gamma : i = 1, \dots, m\}$ collocation points

$$\tilde{\mathbf{u}}(x_i) = \mathbf{g}(x_i), x_i \in \mathcal{X}$$

$B(\omega, \mathcal{X}, \mathcal{Y})$

$$\begin{bmatrix} \mathbb{G}_\omega(x_1 - y_1) & \cdots & \mathbb{G}_\omega(x_1 - y_n) \\ \vdots & \ddots & \vdots \\ \mathbb{G}_\omega(x_m - y_1) & \cdots & \mathbb{G}_\omega(x_m - y_n) \end{bmatrix} \begin{bmatrix} \mathbf{a}_1 \\ \vdots \\ \mathbf{a}_n \end{bmatrix} = \begin{bmatrix} \mathbf{g}(x_1) \\ \vdots \\ \mathbf{g}(x_m) \end{bmatrix} \quad \begin{matrix} (md) \times (nd) \\ \text{Linear System} \end{matrix}$$

- Solving the Linear System: **collocation** (if $n = m$) or **least squares** (if $n > m$)
- Regularization is required: Truncates Singular Value Decomposition (**TSVD**)

• Theoretical Results (homogeneous BVP)

$$\mathcal{S}_D(\Gamma, \hat{\Gamma}) = \text{span}\{\mathbb{G}_\omega(x - y)|_{x \in \Gamma} : y \in \hat{\Gamma}\}$$

MFS approximation space

- Assume that $\omega > 0$ is not an eigenfrequency for the Dirichlet BVP in Ω

Lemma: The restrictions to Γ of $\mathbb{G}_\omega(\cdot - y_1), \dots, \mathbb{G}_\omega(\cdot - y_n)$ are linearly independent.

Theorem [Density result]: For $r \geq 1/2$ the space $\mathcal{S}_D(\Gamma, \hat{\Gamma})$ is dense in $[H^r(\Gamma)]^d$.

Proof:

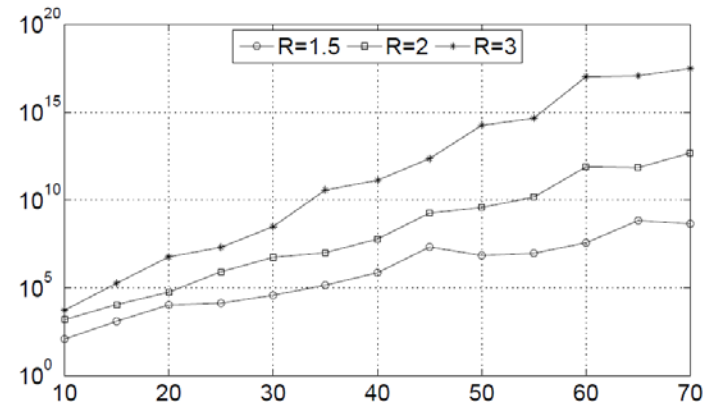
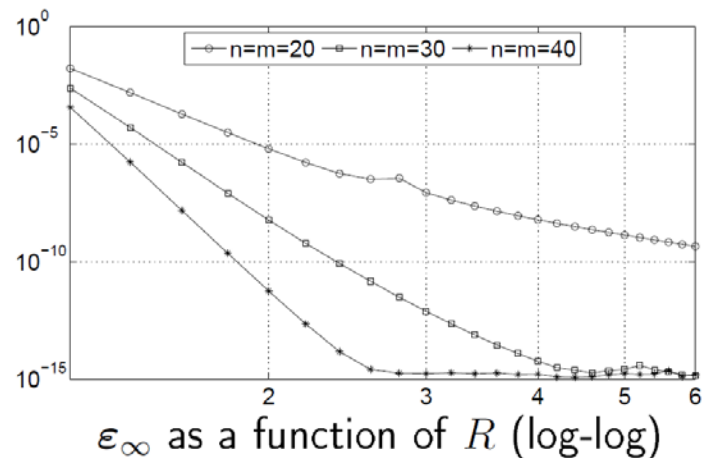
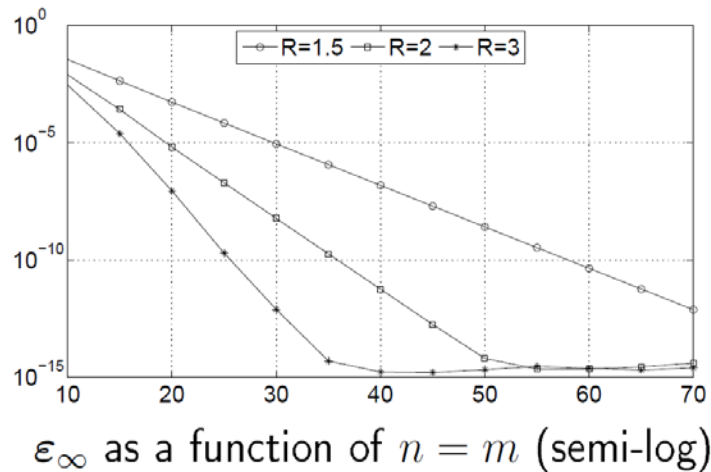
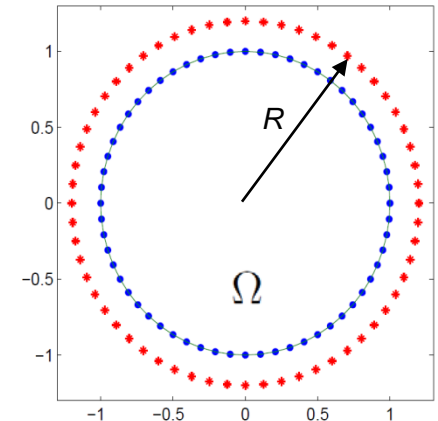
$$\hat{\mathcal{L}} : [H^{r-1}(\hat{\Gamma})]^d \rightarrow [H^r(\Gamma)]^d \quad \xrightarrow{\langle \hat{\mathcal{L}}\varphi, \phi \rangle = \langle \varphi, \hat{\mathcal{L}}^*\phi \rangle} \quad \hat{\mathcal{L}}^* : [H^{-r}(\Gamma)]^d \rightarrow [H^{-r+1}(\hat{\Gamma})]^d$$

$$(\hat{\mathcal{L}}\varphi)(x) = \int_{\hat{\Gamma}} \mathbb{G}_\omega(x - y)\varphi(y) ds_y \quad (\hat{\mathcal{L}}^*\phi)(y) = \int_{\Gamma} \overline{\mathbb{G}_\omega}(x - y)\phi(x) ds_x$$

- $\mathcal{S}_D(\Gamma, \hat{\Gamma})$ is dense in $\mathcal{R}(\hat{\mathcal{L}})$ (discretization argument);
- $[\mathcal{R}(\hat{\mathcal{L}})]^\perp = \ker(\hat{\mathcal{L}}^*)$ (bounded linear operators acting between Banach spaces);
- it is sufficient to show that $\ker(\hat{\mathcal{L}}^*) = \{0\}$.

Typical Numerical Behavior of the MFS (*circular domain*)

- $\Omega = B(0, 1) \subset \mathbb{R}^2$, $\hat{\Gamma} = S_R^1$ ($R > 1$), $\lambda = 1$, $\mu = 2$, $\rho = 1$, $\omega = 1$
- $g(x) = \mathbf{d}e^{ik_p x \cdot \mathbf{d}} + \mathbf{d}^\perp e^{ik_s x \cdot \mathbf{d}}$ with $\mathbf{d} = (1, 1)/\sqrt{2}$ (P-wave & S-wave)
- Remark: choose $n = m$ for higher accuracy (smooth settings)



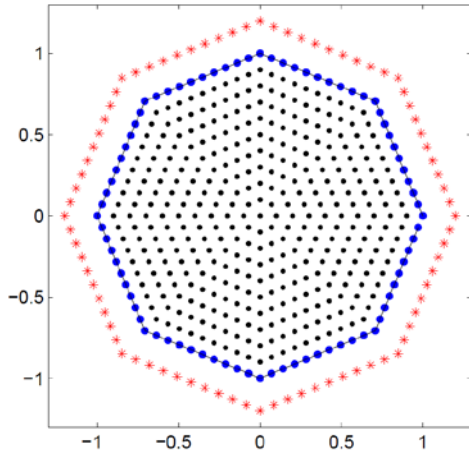
- Exponential convergence with $n = m$
- Algebraic convergence with R
- Trade-off between accuracy and conditioning

Non Homogeneous PDE

• The MFS for nonhomogeneous PDEs

$$\begin{cases} \Delta^* \mathbf{u} + \rho \omega^2 \mathbf{u} = \mathbf{f} & \text{in } \Omega \\ \mathbf{u} = \mathbf{g} & \text{on } \Gamma \end{cases}$$

$$\tilde{\mathbf{u}}(x) = \sum_{r=1}^p \sum_{j=1}^n \mathbb{G}_{\omega_r}(x - y_j) \cdot \mathbf{a}_{r,j} \quad \mathbf{a}_{r,j} \in \mathbb{C}^d, \quad x \in \bar{\Omega}$$



$$\left. \begin{aligned} \mathcal{Y} &= \{y_j \in \hat{\Gamma} : j = 1, \dots, n\} \\ \mathcal{W} &= \{\omega_r > 0 : r = 1, \dots, p\} \end{aligned} \right\} \text{DOF}$$

$$\left. \begin{aligned} \mathcal{X}_0 &= \{x_i \in \Sigma : i = 1, \dots, m_0, \bar{\Omega} \subseteq \Sigma \subset \hat{\Omega}\} \\ \mathcal{X}_1 &= \{x_i \in \Gamma : i = 1, \dots, m_1\} \end{aligned} \right\} \text{collocation points}$$

$$\begin{bmatrix} \rho(\omega^2 - \omega_1^2) \mathbf{B}(\omega_1, \mathcal{X}_0, \mathcal{Y}) & \dots & \rho(\omega^2 - \omega_p^2) \mathbf{B}(\omega_p, \mathcal{X}_0, \mathcal{Y}) \\ \mathbf{B}(\omega_1, \mathcal{X}_1, \mathcal{Y}) & \dots & \mathbf{B}(\omega_p, \mathcal{X}_1, \mathcal{Y}) \end{bmatrix} \begin{bmatrix} \mathbf{a}_{1,1} \\ \vdots \\ \mathbf{a}_{p,n} \end{bmatrix} = \begin{bmatrix} \mathbf{f}(\mathcal{X}_0) \\ \mathbf{g}(\mathcal{X}_1) \end{bmatrix} \quad \begin{array}{l} \text{Linear system} \\ [d(m_0 + m_1)] \times [dnp] \end{array}$$

† Note that $(\Delta^* + \rho \omega^2) \mathbb{G}_{\omega_r} = \rho(\omega^2 - \omega_r^2) \mathbb{G}_{\omega_r}$ since $\Delta^* \mathbb{G}_{\omega_r} = -\omega_r^2 \mathbb{G}_{\omega_r}$ (no differentiation)

- Solving the Linear System: **collocation** (if $n = m$) or **least squares** (if $n > m$)
- Regularization is required: Truncates Singular Value Decomposition (**TSVD**)

• Theoretical Results (density result and error bound)

Theorem [Density result]: $\mathcal{S} = \text{span}\{\mathbb{G}_\omega(x-y)|_{x \in \Omega} : y \in \hat{\Gamma}, \omega \in \mathbb{R}^+\}$ is dense in $[L^2(\Omega)]^d$.

$$\tilde{\mathbf{f}}(x) = \sum_{r=1}^p \sum_{j=1}^n \mathbb{G}_{\omega_r}(x - y_j) \cdot \mathbf{a}_{r,j}, \quad x \in \bar{\Omega} \quad \text{such that} \quad \|\mathbf{f} - \tilde{\mathbf{f}}\|_{[L^2(\Omega)]^d} \leq \varepsilon_1$$

$$\tilde{\mathbf{u}}_P(x) = \sum_{r=1}^p \sum_{j=1}^n \frac{1}{\rho(\omega^2 - \omega_r^2)} \mathbb{G}_{\omega_r}(x - y_j) \cdot \mathbf{a}_{r,j}, \quad x \in \bar{\Omega} \quad \text{satisfies} \quad (\Delta^* + \rho\omega^2) \tilde{\mathbf{u}}_P = \tilde{\mathbf{f}}$$

$$\mathbf{u} = \mathbf{u}_P + \mathbf{u}_H \quad \approx \quad \tilde{\mathbf{u}} = \tilde{\mathbf{u}}_P + \tilde{\mathbf{u}}_H$$

$$\begin{cases} (\Delta^* + \rho\omega^2) \mathbf{u}_P = \mathbf{f} & \text{in } \Omega \\ \mathbf{u}_P = \tilde{\mathbf{u}}_P & \text{on } \Gamma \end{cases}$$

↓ well posedness

$$\|\mathbf{u}_P - \tilde{\mathbf{u}}_P\|_{[H^1(\Omega)]^d} \leq C_1 \varepsilon_1$$

$$\begin{cases} (\Delta^* + \rho\omega^2) \mathbf{u}_H = 0 & \text{in } \Omega \\ \mathbf{u}_H = \mathbf{g} - \tilde{\mathbf{u}}_P & \text{on } \Gamma \end{cases}$$

↓ classical MFS

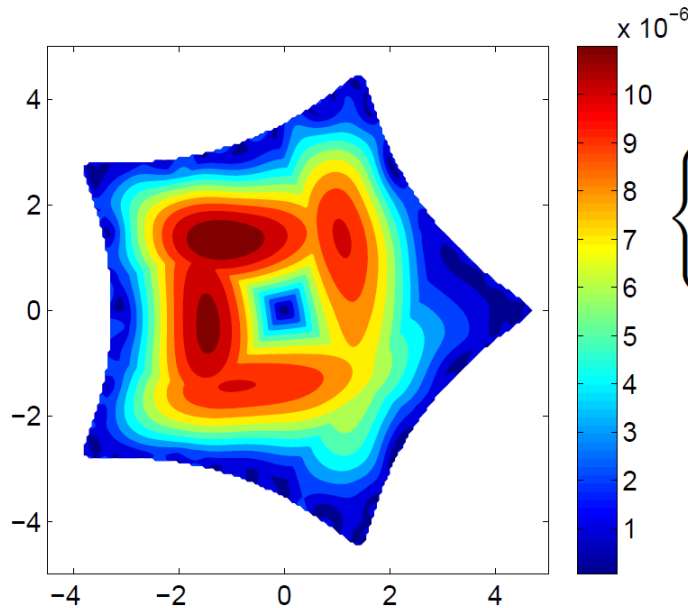
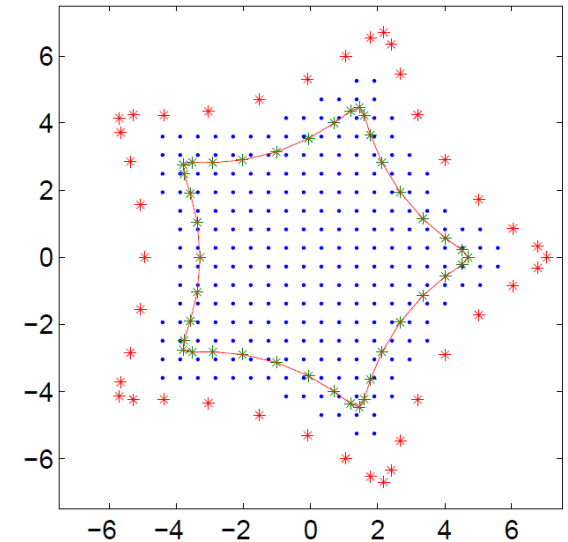
$$\|\mathbf{u}_H - \tilde{\mathbf{u}}_H\|_{[H^1(\Omega)]^d} \leq \varepsilon_2$$

Choose ε_1 and ε_2 such
that $C_1 \varepsilon_1 + \varepsilon_2 \leq \varepsilon$

$$\|\mathbf{u} - \tilde{\mathbf{u}}\|_{[H^1(\Omega)]^d} \leq \|\mathbf{u}_P - \tilde{\mathbf{u}}_P\|_{[H^1(\Omega)]^d} + \|\mathbf{u}_H - \tilde{\mathbf{u}}_H\|_{[H^1(\Omega)]^d} \leq \varepsilon$$

Numerical Example #1 (*known exact solution*)

- Parametric domain: $z(t) = 4e^{it} + 0.7e^{-4it}$, $t \in [0, 2\pi]$;
- $\lambda = 2$, $\mu = 2$, $\omega = 2$, $\rho = 1$;
- $\mathbf{u}(x) = \left\{ \begin{array}{l} i \cos(x_1 - x_2) - \sin(x_1 - x_2) \\ i \exp(-x_1^2) + \cos(x_1 + x_2) \end{array} \right\}$;
- $\hat{\Gamma} = 2.5 \times \Gamma$, $n = 40$, $\Sigma = 1.3 \times \bar{\Omega}$, $m_0 = 974$, $m_1 = 140$.



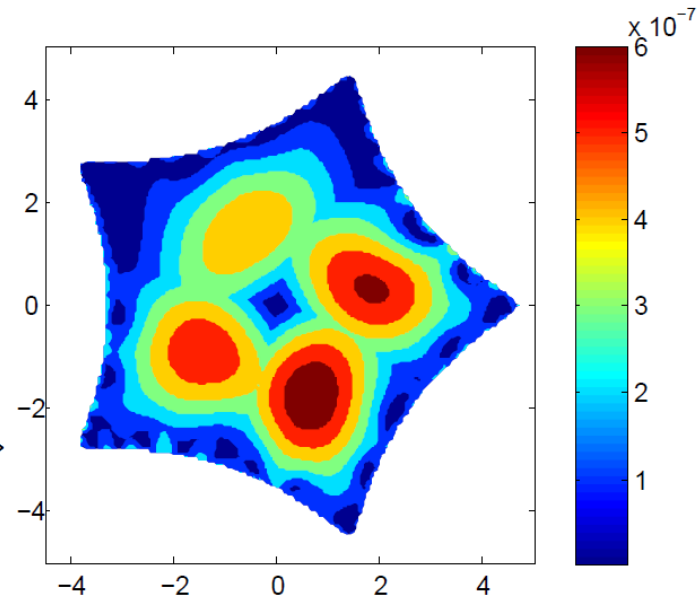
$$\mathcal{W} = \{\sqrt{i^2 + j^2} : i, j = 1, \dots, 6\}$$

RMS error

$$\left\{ \begin{array}{l} \Gamma : 1.61 \times 10^{-6} \\ \Omega : 3.16 \times 10^{-6} \end{array} \right.$$

$$\left. \begin{array}{l} \Gamma : 1.73 \times 10^{-7} \\ \Omega : 8.07 \times 10^{-7} \end{array} \right\}$$

$$p = 21$$

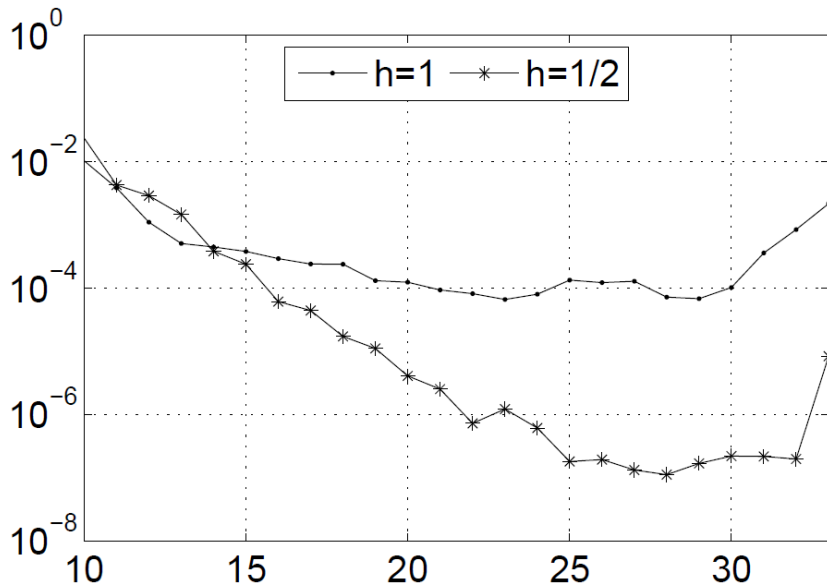


$$\mathcal{W} = \{0.5 : 0.5 : 10.5\}$$

Numerical Example #1 (cont.) – Convergence

- Error decreases with the number of collocation points (m_0, m_1)
- Error decreases with the number of source points (n)
- Error decreases with the distance between Γ and $\hat{\Gamma}$
- Condition number of the linear system increases with m_0, m_1, n and p
- Error decreases with the number of test frequencies (p)

Like in MFS



- The choice of \mathcal{W} is of the utmost importance

← $\mathcal{W}_1 = \{i : i = 1, 2, \dots, p\}$

← $\mathcal{W}_{1/2} = \{i/2 : i = 1, 2, \dots, p\}$

The error $\varepsilon_\infty^\Omega$ as a function of $\#\mathcal{W}$

Highly accurate numerical results may be achieved only by varying all the parameters simultaneously. Parameters $\hat{\Gamma}, \Sigma, m_0, m_1, n, p$ are interdependent.

Numerical Example #1 (cont.) – Higher Accuracy

PDE residuals $R_i^\Omega = f(x_i) - (\Delta^* + \rho\omega^2)\tilde{u}(x_i), \quad x_i \in \mathcal{X}_0$

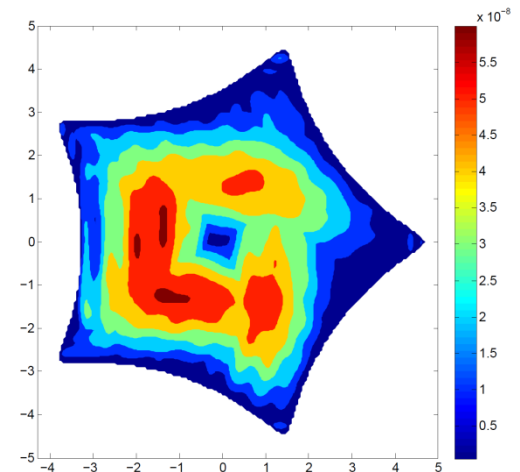
BC residuals $R_i^\Gamma = g(x_i) - \tilde{u}(x_i), \quad x_i \in \mathcal{X}_1$

Least squares functional $J = \frac{1}{2} \left(\sum_{i=1}^{m_0} [R_i^\Omega]^2 + \alpha \sum_{i=1}^{m_1} [R_i^\Gamma]^2 \right)$ α - penalty coefficient

α - relative weight of the boundary residuals with respect to the interior residuals

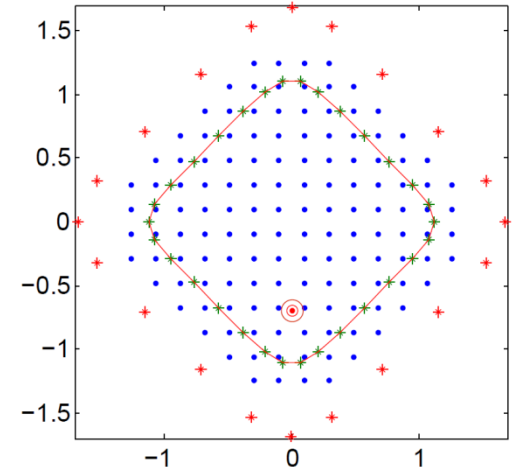
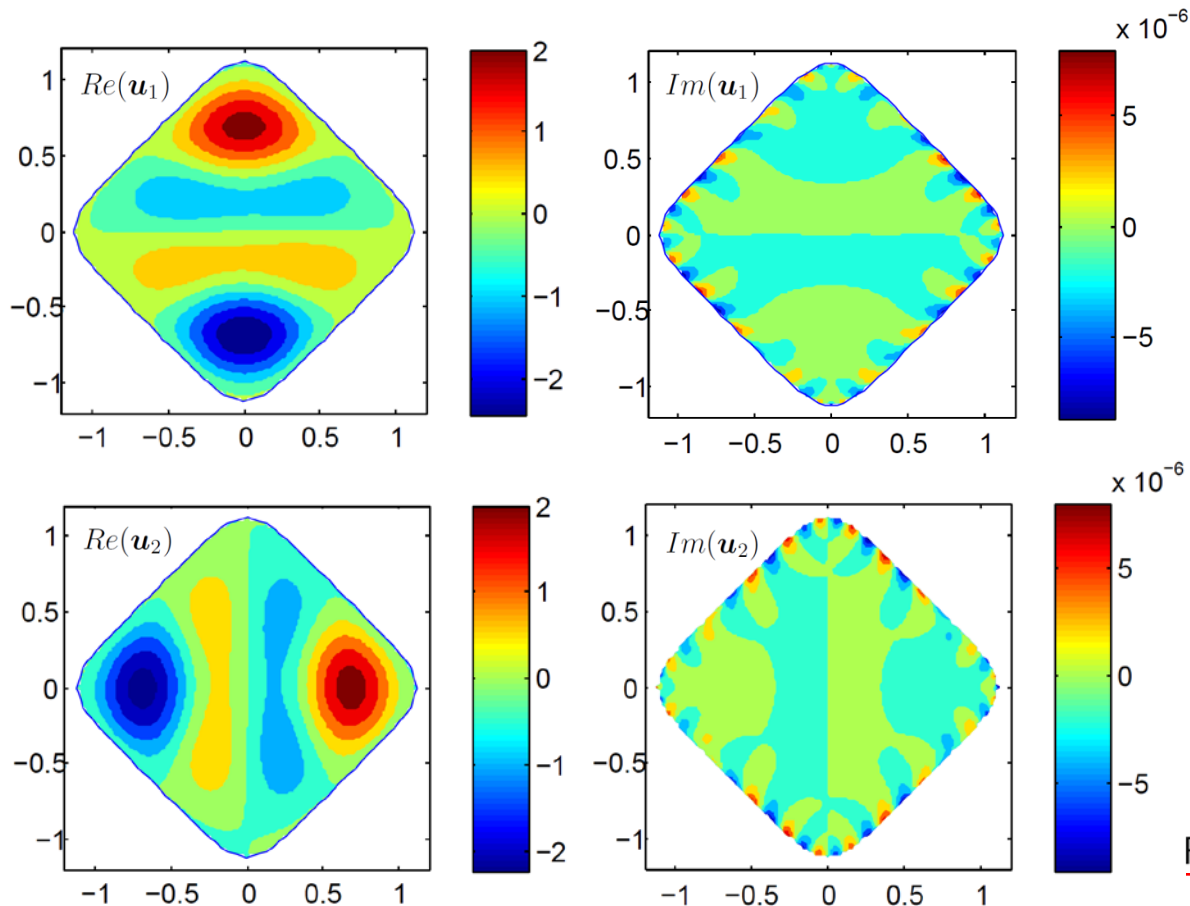
$$\begin{bmatrix} \rho(\omega^2 - \omega_1^2)\mathbf{B}(\omega_1, \mathcal{X}_0, \mathcal{Y}) & \dots & \rho(\omega^2 - \omega_p^2)\mathbf{B}(\omega_p, \mathcal{X}_0, \mathcal{Y}) \\ \alpha \mathbf{B}(\omega_1, \mathcal{X}_1, \mathcal{Y}) & \dots & \alpha \mathbf{B}(\omega_p, \mathcal{X}_1, \mathcal{Y}) \end{bmatrix} \begin{bmatrix} \mathbf{a}_{1,1} \\ \vdots \\ \mathbf{a}_{p,n} \end{bmatrix} = \begin{bmatrix} \mathbf{f}(\mathcal{X}_0) \\ \alpha \mathbf{g}(\mathcal{X}_1) \end{bmatrix} \quad \begin{array}{l} \text{Least squares} \\ + \\ \text{Regularization} \end{array}$$

α	$\varepsilon_\infty^\Omega$	$\varepsilon_\infty^\Gamma$	ε_∞^{PDE}
1	6.8073×10^{-7}	3.6926×10^{-7}	8.8277×10^{-6}
50	1.7285×10^{-7}	1.6129×10^{-8}	7.9281×10^{-6}
100	8.5050×10^{-8}	8.4475×10^{-9}	6.6461×10^{-6}
150	6.2990×10^{-8}	6.0600×10^{-9}	5.6295×10^{-6}
200	3.5755×10^{-7}	4.4197×10^{-9}	6.6751×10^{-6}



Numerical Example #2 (*interior wave scattering*)

- $\mathbf{g}(x) = -\mathbf{u}^{inc}(x) = -\text{Re}[\mathbb{G}_\omega(x - S)\mathbf{e}_1]$ with $S = (0, -0.7)$;
- $\mathbf{f}(x) = \{\sin(x_1 + x_2); \cos(x_1 + x_2)\}$;
- $\lambda = 2, \mu = 2, \rho = 1, \omega = 10$;
- $\hat{\Gamma} = 2.5 \times \Gamma, n = 50, \Sigma = 1.3 \times \bar{\Omega}, m_0 = 1228, m_1 = 300, p = 28$.



- Linear system: 3056×2800
- Condition number: $\sim 10^{30}$
- TSVD residual error: 1.75×10^{-4}

RMS error

- $\|\mathbf{g} - \tilde{\mathbf{u}}\|_\Gamma = 7.1377 \times 10^{-6}$
- $\|\mathbf{f} - \mathcal{E}\tilde{\mathbf{u}}\|_\Omega = 3.9820 \times 10^{-7}$

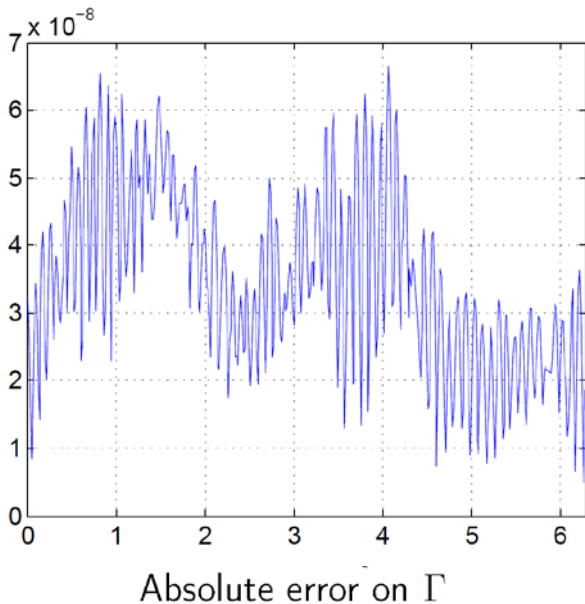
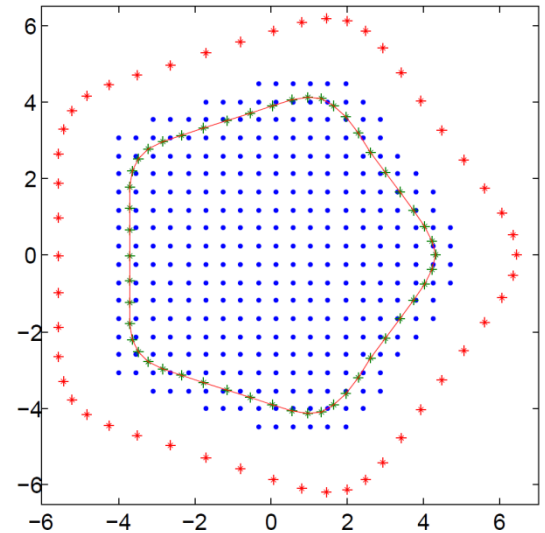
Remark: $\text{Im}(\tilde{\mathbf{u}}) \sim 10^{-6}$ (neglectable)

Numerical Example #3 (more general PDEs)

$$\begin{cases} \Delta^* \mathbf{u} + a \mathbf{u} = \mathbf{f} & \text{in } \Omega \\ \mathbf{u} = \mathbf{g} & \text{on } \Gamma \end{cases}$$

$$a(x) = 2 + \sin(x_1 + x_2)$$

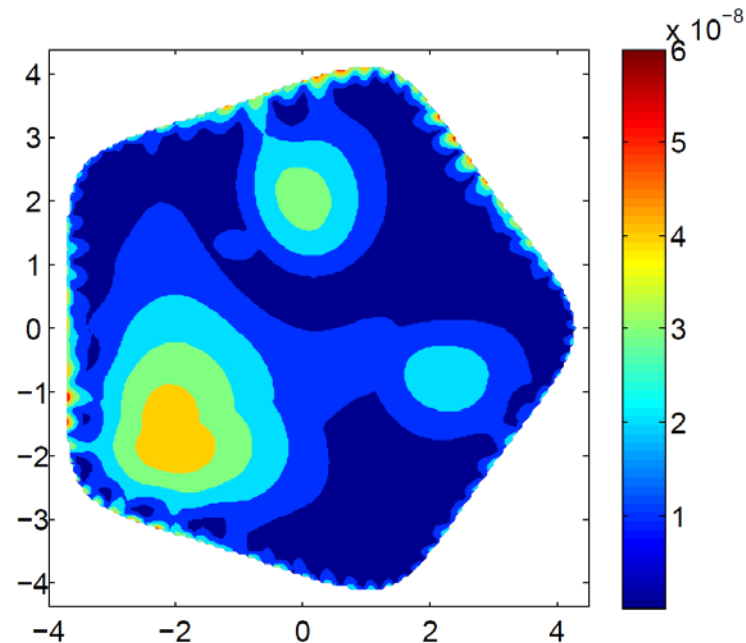
- $\lambda = 2, \mu = 2$;
- $\mathbf{u}(x) = \begin{Bmatrix} i \cos(x_1 - x_2) - \sin(x_1 - x_2) \\ i \exp(-x_1^2) + \cos(x_1 + x_2) \end{Bmatrix}$;
- $\hat{\Gamma} = 1.5 \times \Gamma, n = 50, \Sigma = 1.2 \times \bar{\Omega}, m_0 = 1910, m_1 = 150$;
- $\mathcal{W} = \{0.5 : 0.5 : 12\}, p = 24$.



- Linear system: 4120×2400
- Condition number: $\sim 10^{18}$
- TSVD residual error: 1.65×10^{-6}

RMS error

- $\|\mathbf{g} - \tilde{\mathbf{u}}\|_{\Gamma} = 3.0631 \times 10^{-8}$
- $\|\mathbf{f} - \mathcal{E}\tilde{\mathbf{u}}\|_{\Omega} = 2.2899 \times 10^{-8}$
- $\|\mathbf{g} - \tilde{\mathbf{u}}\|_{\Omega} = 6.1813 \times 10^{-8}$



• Publications

- Carlos J. S. Alves, Nuno F. M. Martins and Svilen S. Valtchev, Extending the method of fundamental solutions to non homogeneous elastic wave problems, submitted, 2015.
- Pedro R. S. Antunes, Svilen S. Valtchev, A meshfree numerical method for acoustic wave propagation problems in planar domains with corners and cracks, J Comput. Appl. Math, 234, pp. 2646-2662, 2010.
- Svilen S. Valtchev, Asymptotic analysis of the method of fundamental solutions for acoustic wave propagation, Numerical Analysis and Applied Mathematics, AIP Conference Proceedings, vol. 1281, pp. 1179-1182, 2010.
- Svilen S. Valtchev, Nilson C. Roberty, A time-marching MFS scheme for heat conduction problems, Eng. Analysis Bound. Elements, 32, pp. 480-493, 2008.
- Carlos J. S. Alves, Svilen S. Valtchev, A Kansa Type Method Using Fundamental Solutions Applied to Elliptic PDEs, Advances in Meshfree Techniques, Computational Methods in Applied Sciences, vol. 5, Springer, 2006.
- Carlos J. S. Alves, Svilen S. Valtchev, Numerical comparison of two meshfree methods for acoustic wave scattering, Eng. Analysis Bound. Elements, 29, pp. 371-382, 2005.